#### **Understanding the Root Cause of Poor Seismic Data Through Modelling\***

#### Anastasia Poole<sup>1</sup> and Peter V. Baaren<sup>1</sup>

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#### **Abstract**

Enabled by ongoing advances in computer technology and processing algorithms, pre-acquisition feasibility studies using synthetic data are becoming more and more accepted in the marine environment. For marine acquisition the near-surface is relatively simple acoustic medium which simplifies the computational task for synthetic modelling, enabling large-scale 3D seismic simulations for various scenarios to be run within a reasonable time frame. In comparison with onshore acquisition the near surface is a much more complex elastic medium which makes finite- difference simulation modelling significantly more compute intensive.

Through developments in modelling and inversion technology a suite of tools are now available which allow us to build complex near-surface models without having to revert to full elastic finite-difference modelling. Consequently multiple near-surface models may be generated in a relatively short period of time.

This article demonstrates how it is possible to gain an understanding of the onshore near-surface in absence of direct measurements, such as uphole surveys. We can utilize the existing seismic data to support near-surface model building and the generation of realistic synthetics.

By varying the parameters of the Earth model and comparing synthetic data with the real seismic data, it is possible to gain an understanding of the mechanisms behind the noise trains visible on the real seismic data. We can then analyze how to optimize selection of acquisition parameters and data processing schemes with respect to both signal and noise.

Such analyses can include evaluation of the effects of geometry, fold, arrays and noise interference introduced by high productivity techniques. The article gives a case-study example of such a workflow approach where it was used to uncover the potential root cause of poor legacy seismic data quality.

<sup>\*</sup>Adapted from oral presentation given at GEO 2016, 12<sup>th</sup> Middle East Geosciences Conference & Exhibition, Manama, Bahrain, March 7-10, 2016; presentation by John Quigley.

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#### Reference Cited

Jack, I., 2013, Progress in land seismic technology: Finding Petroleum, Oil Voice Forum, London, 7 March, 2013. 41p. Website accessed September 27, 2016, <a href="http://64be6584f535e2968ea8-7b17ad3adbc87099ad3f7b89f2b60a7a.r38.cf2.rackcdn.com/Jack.2013.OilVoiceForum.March.Rev3.pdf">http://64be6584f535e2968ea8-7b17ad3adbc87099ad3f7b89f2b60a7a.r38.cf2.rackcdn.com/Jack.2013.OilVoiceForum.March.Rev3.pdf</a>.

# Understanding the root cause of poor data through modelling

Anastasia Poole & Peter van Baaren

Presented by John Quigley

GEO2016 08th March 2016, Bahrain



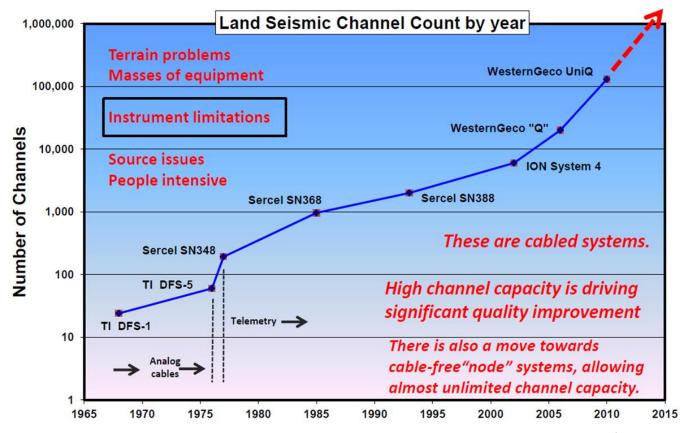
#### Conclusions

#### Modelling allows:

- Separation of contributing factors
  - Signal
  - Coherent noise
  - Ambient noise
- Test both acquisition and processing schemes together
- Test different hypotheses
- Quantify errors

#### Towards "better" data

- Increased fold
- Full azimuth
- Broadband energy
- Point source
- Point receiver
- High trace density

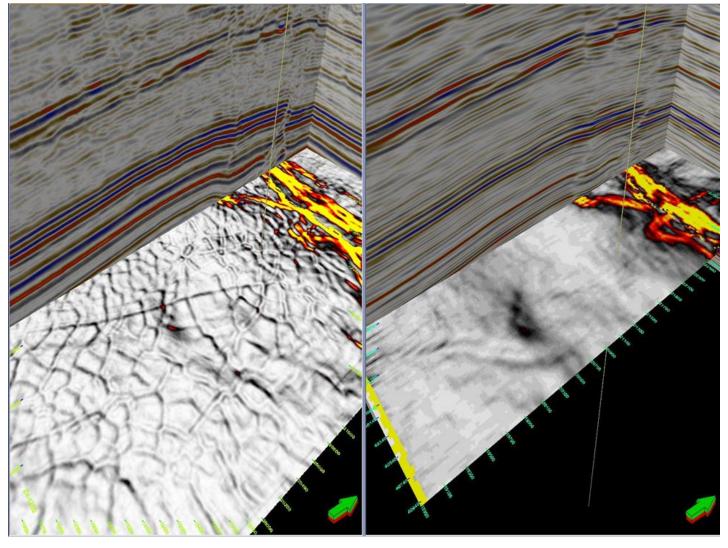


lan Jack, 'Progress in land seismic technology', Finding Petroleum, Oil Voice Forum, London, 7th March 2013

Modelling allows investigating these beliefs before acquiring data

#### **Better data**

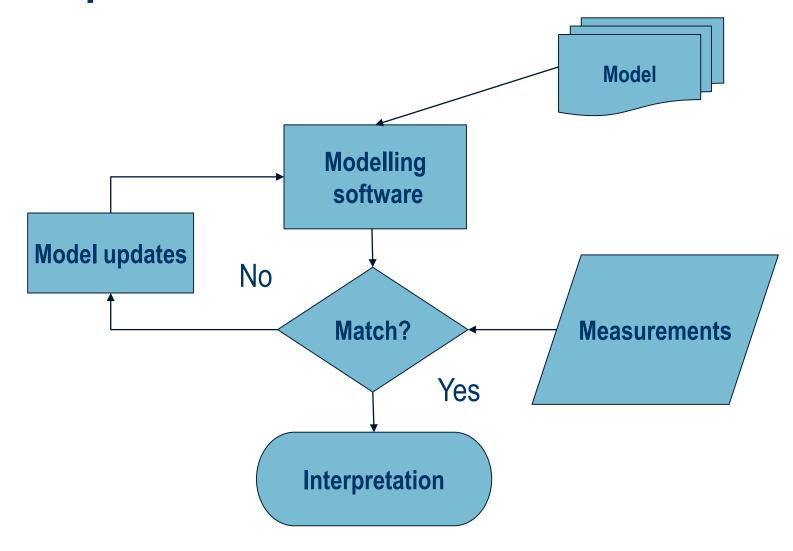
- Good well ties
- Stable wavelet
- Fits geologic model

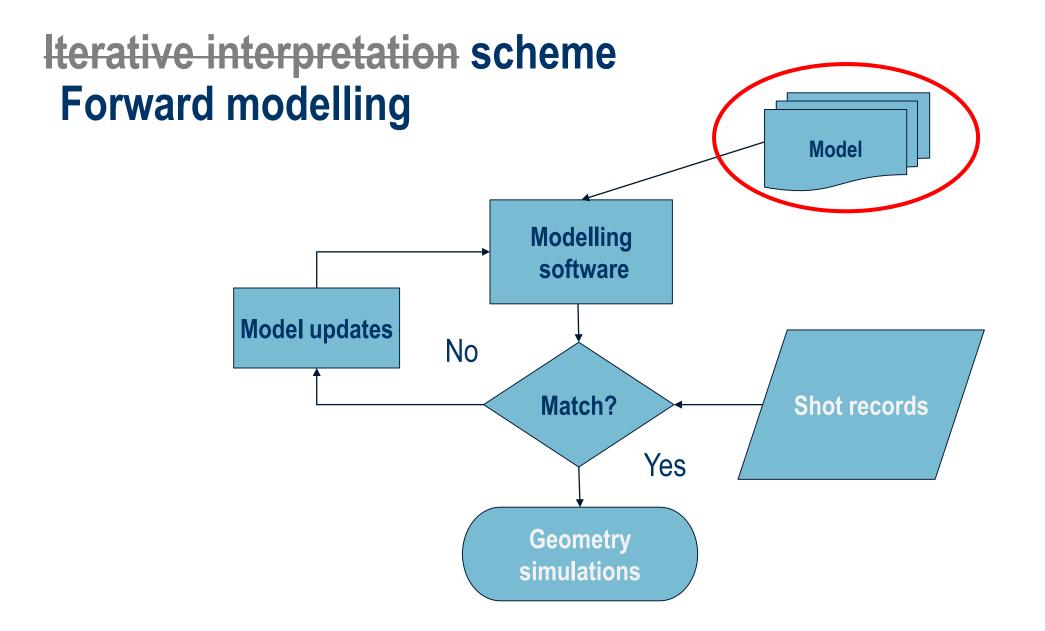


**PSPR Full Offset & Azimuth** 

**Legacy Array Limited Offset & Azimuth** 

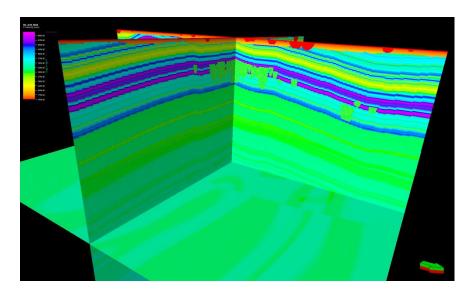
## **Iterative interpretation scheme**

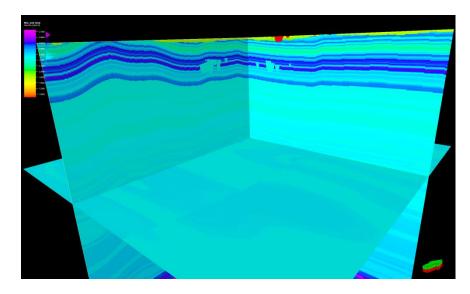




#### Full elastic models - Example 3D model

SEG SEAM Arid Model - 3D depth model with following properties: Vp, Vs, Rho/Density, HTI alpha, HTI delta, HTI gamma, HTI azimuths, Qp

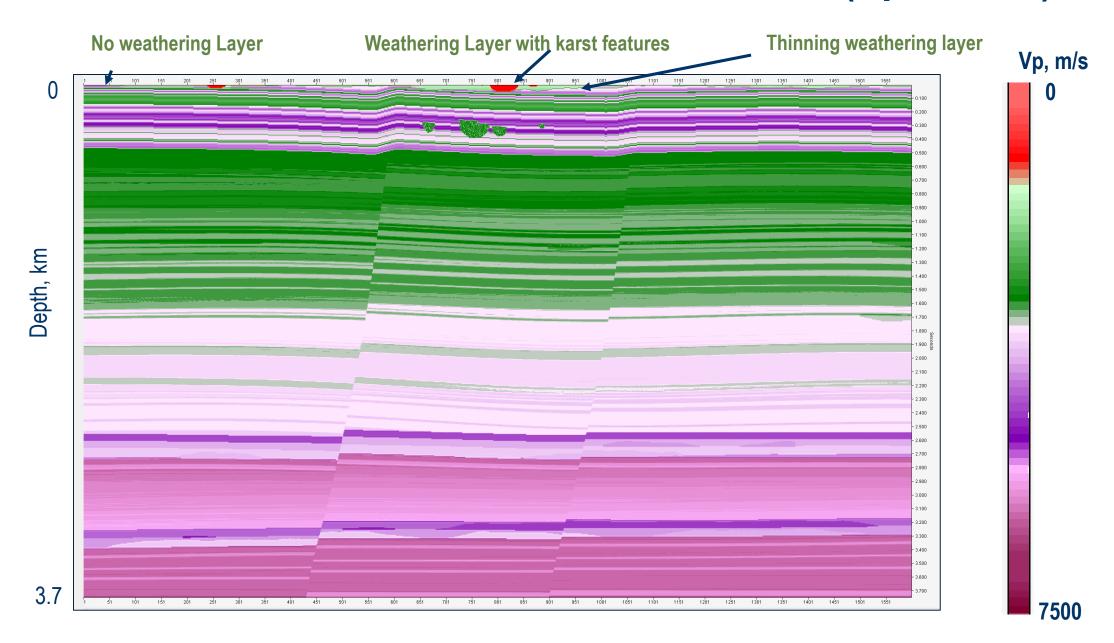




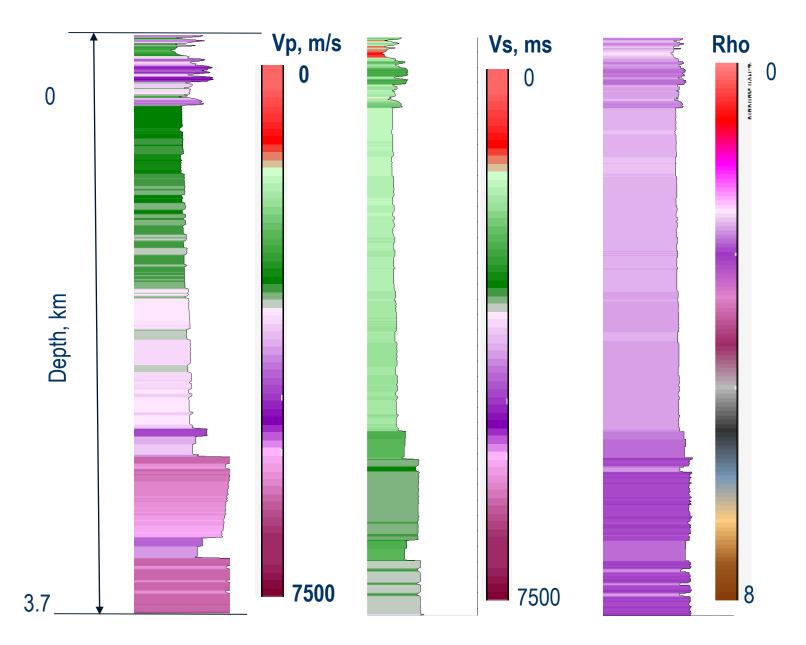
Vp

**Rho / Density** 

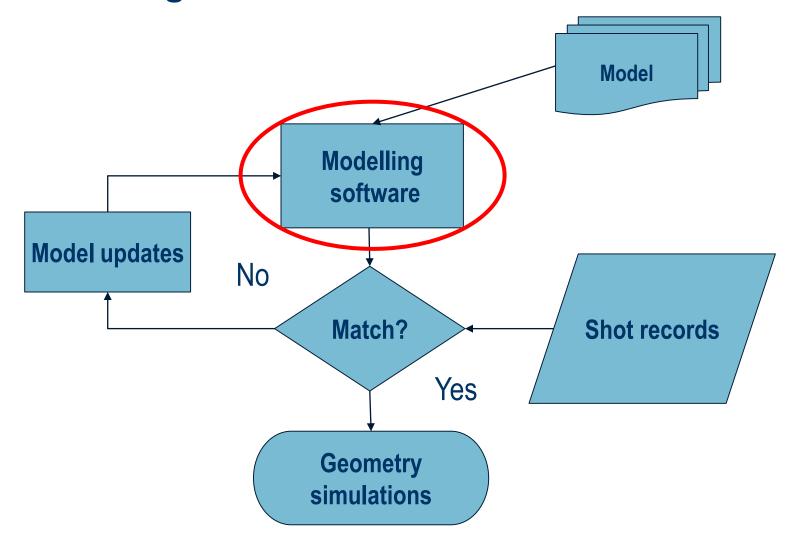
#### Model subset - 2D line from SEAM Arid Model (Vp shown)



#### **Example 1D model extracted from SEAM Arid Model**



# Forward modelling scheme

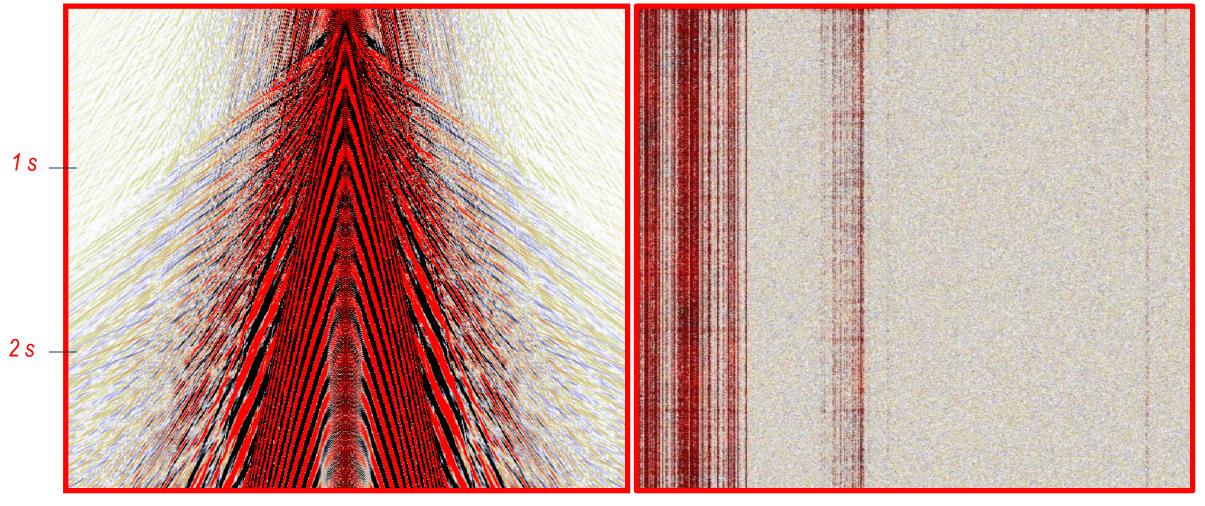


# Elastic wavefield modelling tools

Method	Description	Limitation	Speed
3D Full Elastic	Full 3D Finite-Difference wavefield propagation		Excessive run time for Land 3D models with realistic frequency ranges
2D Full Elastic	Finite-Difference	No out-of-plane energy No out-of-plane scattering	Weeks
1D Full Elastic	ANIVEC (Kennett algorithm)	Layer cake geology No scattering	Days

Variable response
Thinning weathering layer **Weathering Layer with karst features** 18 s. MD Sweep Frequency, Hz 120 0 s 3 s

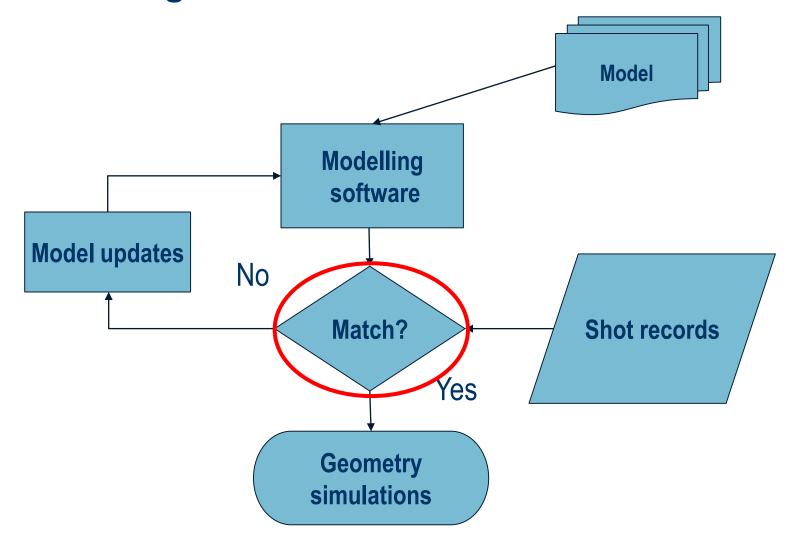
# Realistic synthetic shot records



**Point Source / Point Receiver synthetic signal** 

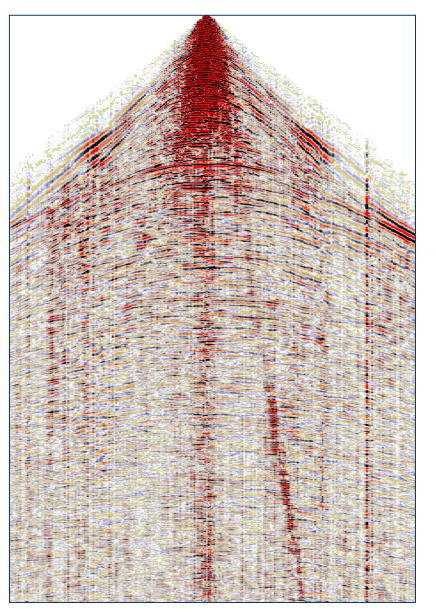
**Synthetic ambient noise model** 

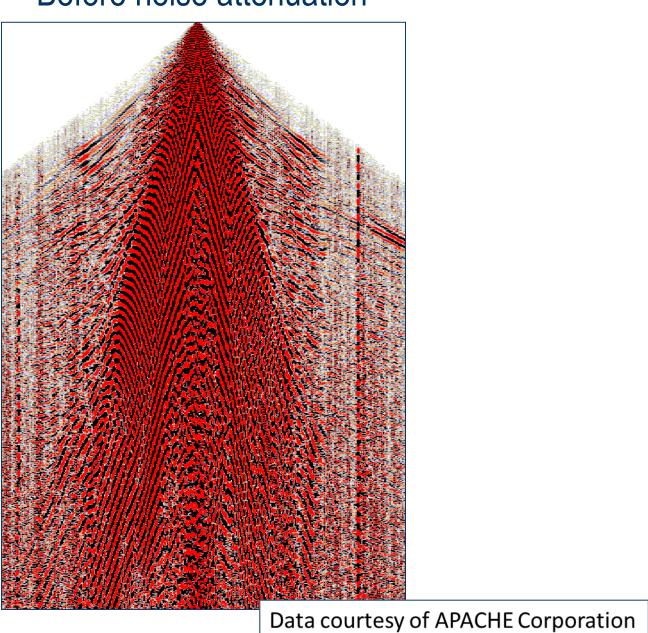
## Forward modelling scheme



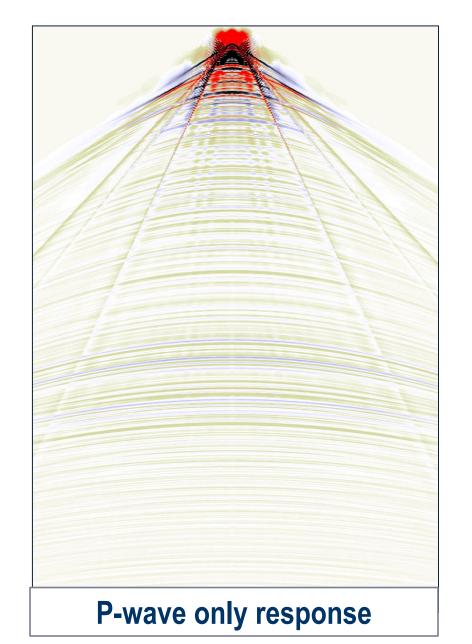
PSPR gather
After noise attenuation

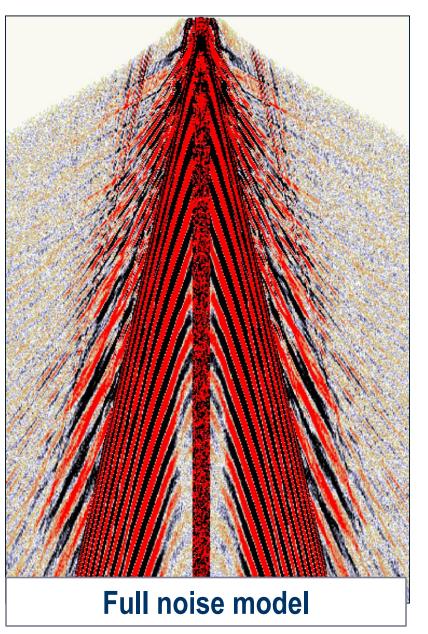
PSPR gather
Before noise attenuation



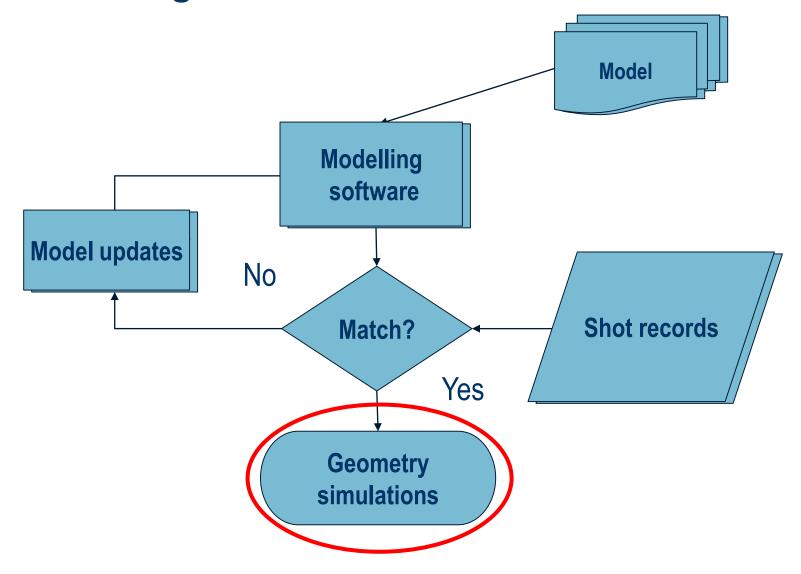


### Point-Source / Point-Receiver synthetic generation

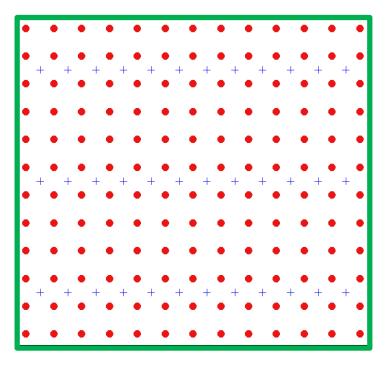




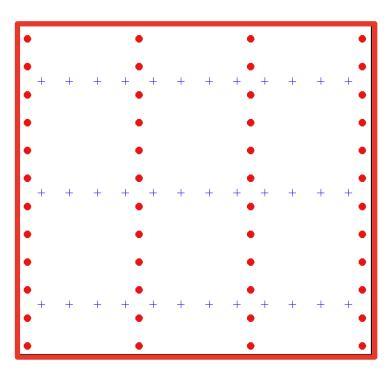
## Forward modelling scheme



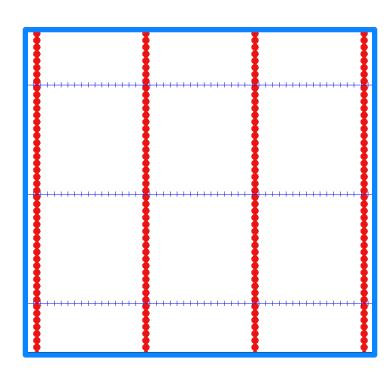
## Modelled acquisition geometries



**Shot-Carpet** 



**Orthogonal Array** 



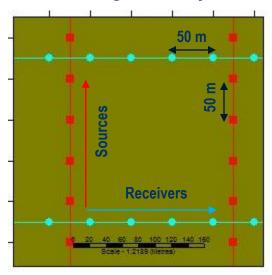
**Point-Source Point-Receiver** 

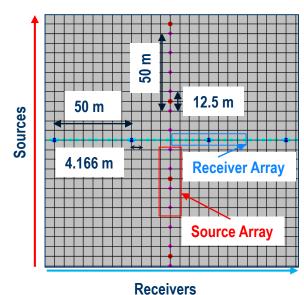
# **Geometry simulations in numbers**

Parameter	Shot-Carpet	Orthogonal Array	PSPR
Source line spacing (m)	50	200	200
Receiver line spacing (m)	200	200	200
Shot point and receiver point spacing, (m)	200	50	12.5
Maximum IL/XL offset (m)	4400	4400	4400
Number of receiver lines	176	44	44
Number of receivers per line	176	176	704
Total active receivers/patch	30976	7744	30976
Natural fold	1936	484	484
Fold 25 m x 25 m bins	1936	484	7744
# Sensors per station	12	12	1
# Vibrators per shot point	4	4	1
Relative noise attenuation power √N	+22.8	+16.8 dB	0 dB

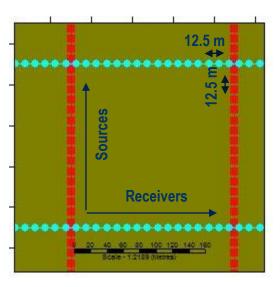
### Orthogonal Array vs Point-Source / Point-Receiver geometry

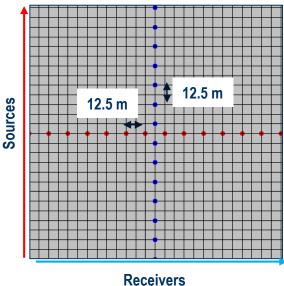




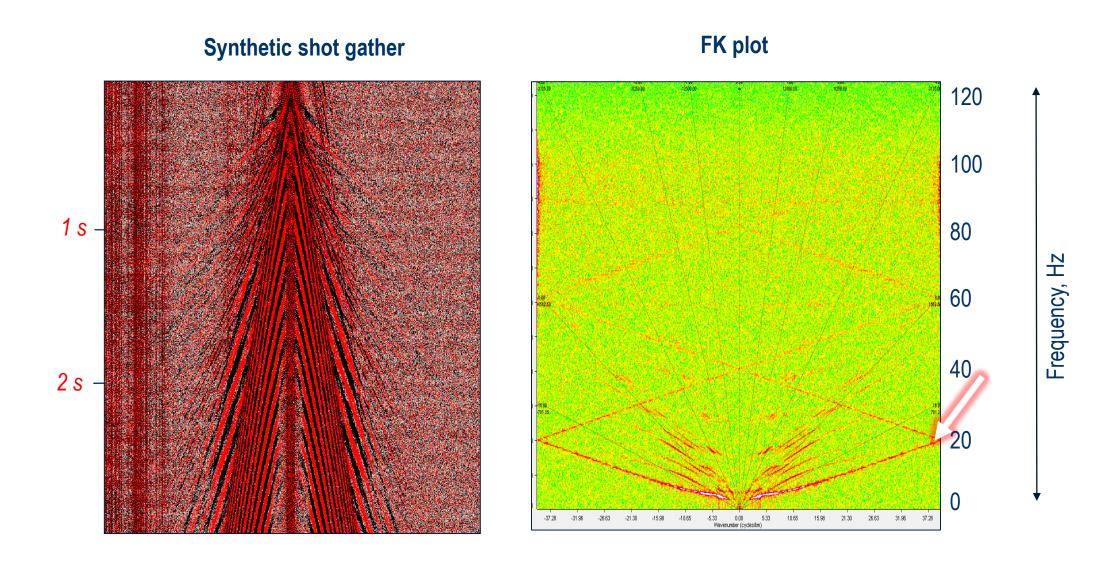


#### Point-Source / Point-Receiver

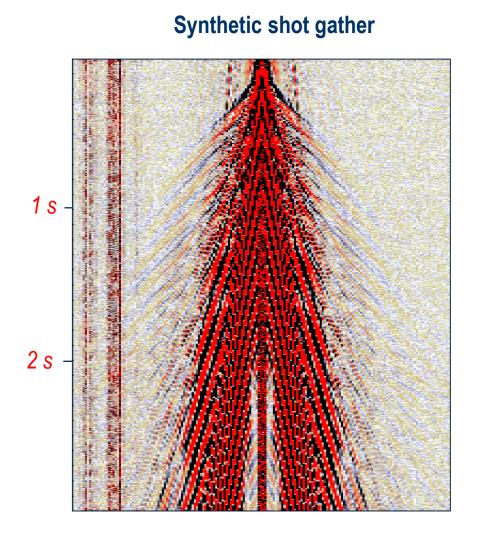


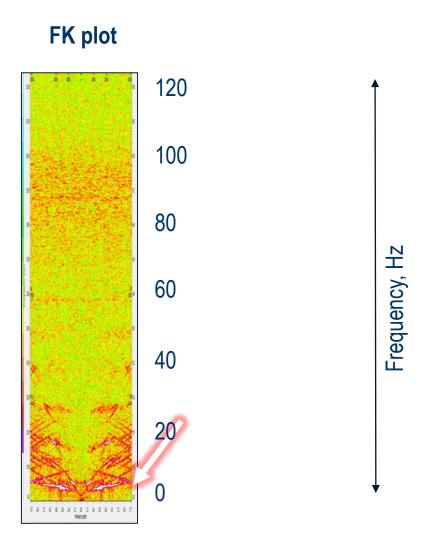


### Point-Source / Point-Receiver synthetic data



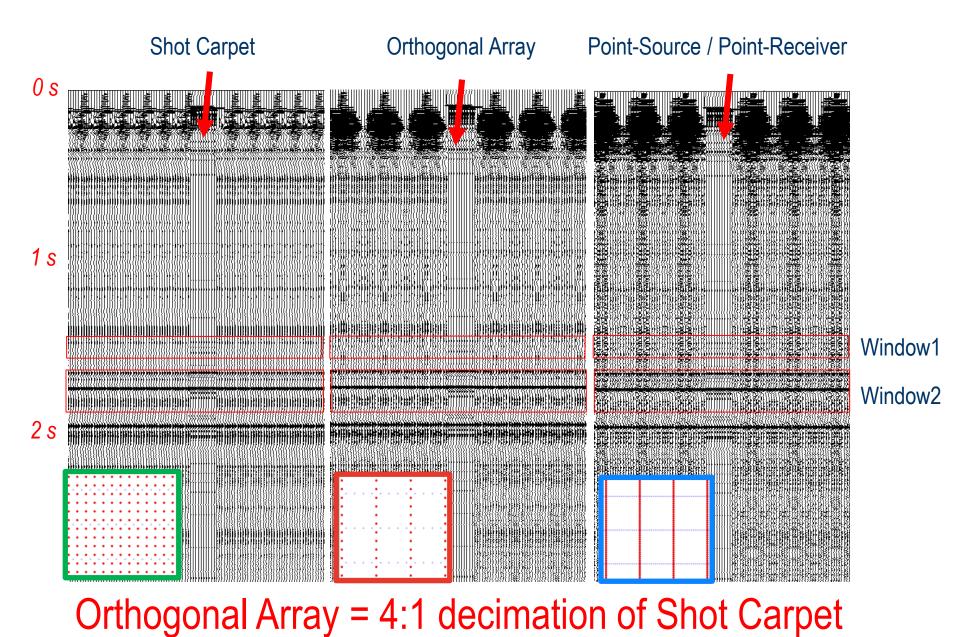
# Orthogonal geophone array synthetic data





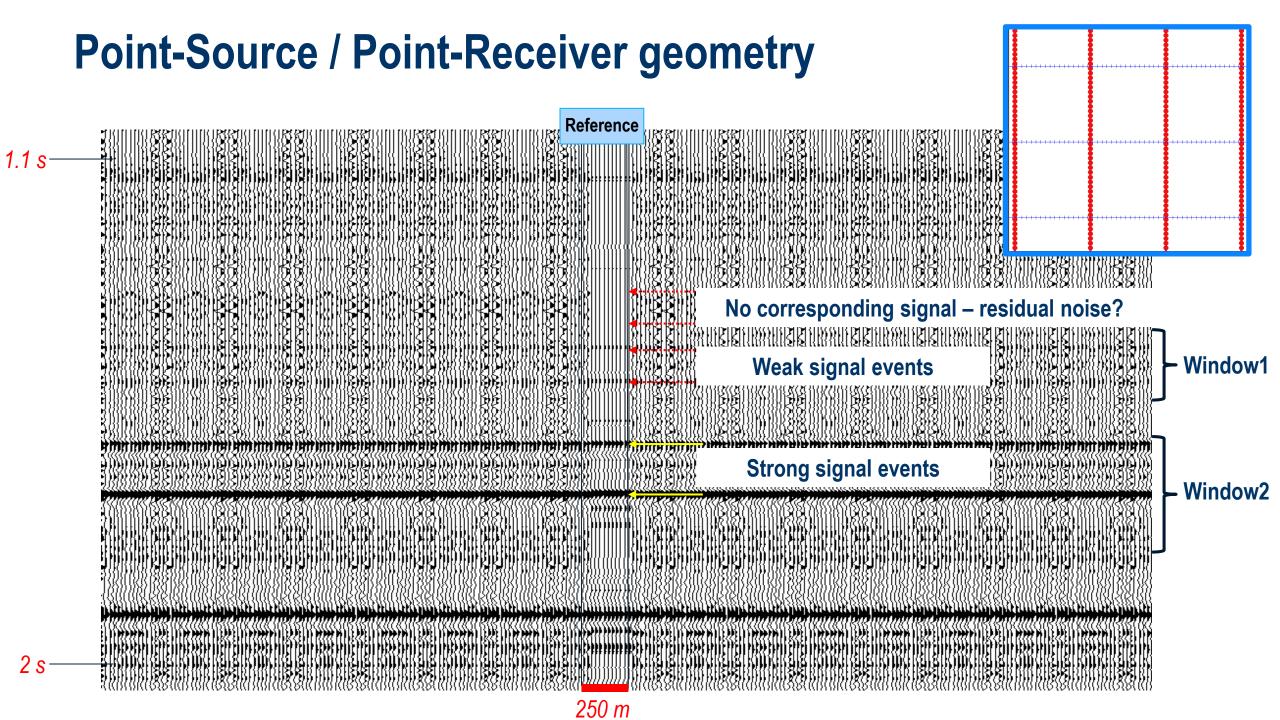
#### **Processing flow** Data First beak picking **Surface consistent Refraction Tomo Statics** amplitude correction **Burst noise attenuation in** shot & receiver domain **Coherent noise attenuation Scattering attenuation Iterations Surface Consistent Deconvolution Velocity Analysis** Regularization **Residual Statics Velocity Analysis Migration and Post** Stack and **Migration Processing Post-Stack Processing**

### Synthetic stack comparison

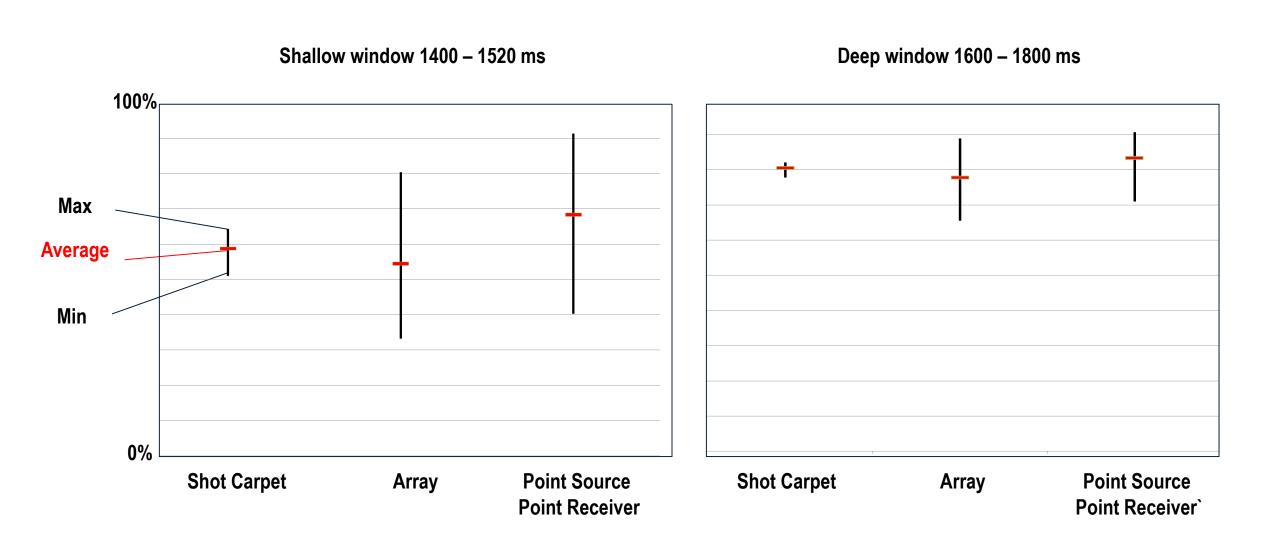


# **Shot-Carpet geometry** Reference No corresponding signal – residual noise? ALLITTALLITTALLITTALLITTALLITTALLITTALLITTALLITTALLITTALLITTALLITTALLITTALLITTALLITTALLITTALLITTALLITTALLITTAL Weak signal events Window1 **Strong signal events** Window2

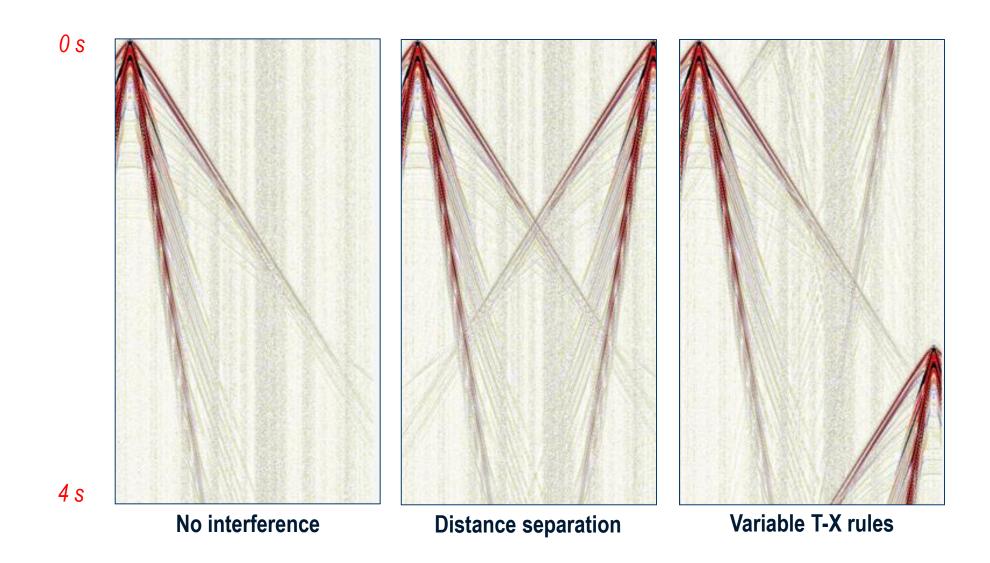
# **Orthogonal Array geometry** Reference No corresponding signal – residual noise? Weak signal events Window1 **Strong signal events** Window2



### **Predictability metrics**



## Productivity enhancement - shot interference



#### **Discussion**

Methodology highlights many "features" of current acquisition and processing practices

- It is easy to create spurious coherent events
- Coherent noise attenuation is a key factor none of the chosen geometries and coherent noise attenuation processing are fully effective in removing noise
- Using √N to rank geometries appears not to provide the correct ranking of the geometries.

#### Conclusions

#### Modelling allows:

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#### **Acknowledgements**

Donnie Enns (OXY) and Scott Burns (formerly OXY) for extensive discussions

SEG Arid Model, courtesy of SEAM Phase II

## **Questions?**

