

# **Spectral Recomposition in Stratigraphic Interpretation\***

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## **Abstract**

Spectral recomposition splits the seismic spectrum into Ricker components. It provides a tool for imaging and mapping temporal bed thicknesses and geologic discontinuities. We propose separable nonlinear least-squares estimation in spectral recomposition. Employing the Gauss-Newton method, separable nonlinear least-squares approach estimates fundamental signal parameters: peak frequencies and amplitudes.

## **References Cited**

Chakraborty, A., and D. Akaya, 1995, Frequency-time decomposition of seismic data using wavelet-based methods: *Geophysics*, v. 60/6, p. 1906-1916.

Chen, G., G. Matteucci, B. Fahmy, and C. Finn, 2008, Spectral-decomposition response to reservoir fluids from a deepwater West Africa reservoir: *Geophysics*, v. 73/6, p. C23-C30.

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# Spectral Recomposition in Stratigraphic Interpretation

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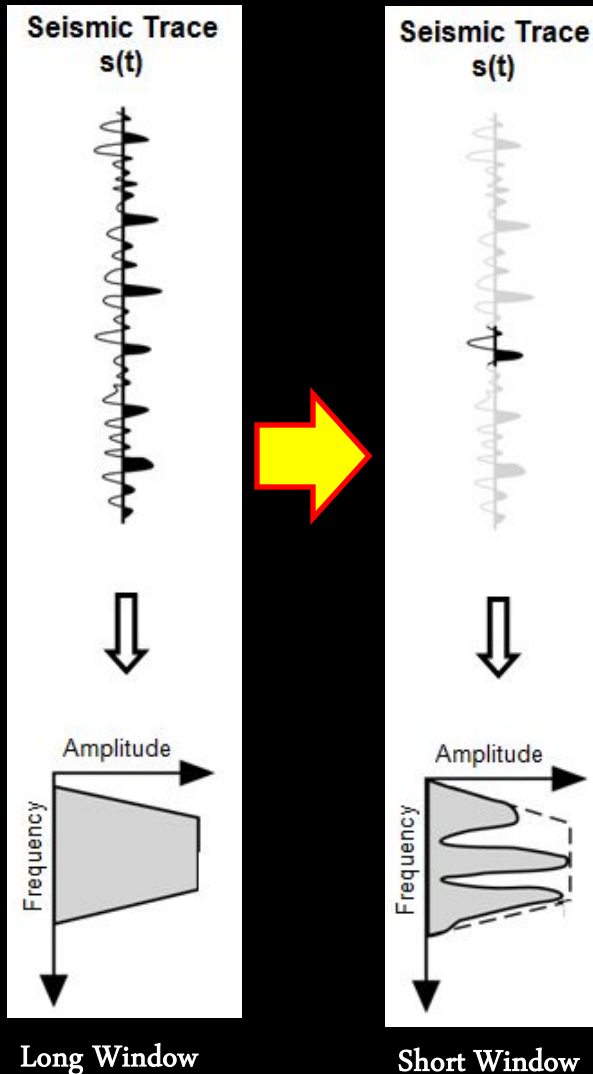
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# Outline

- Motivation and Background
  - Spectral Analysis
  - Spectral Recomposition
- Theory and Numerical Method
  - Theory
  - Numerical Method – Separable Nonlinear Least Squares Estimation
  - Synthetic and Real Data Examples
- Application of Spectral Recomposition
  - Seismic Data Display
  - Stratal Slice Imaging and RGB Color Blending Plot
  - Time-frequency Analysis Estimation
- Summary

# Spectral Analysis



## □ Spectral analysis:

1. Long window vs. short window;
2. Spectral decomposition for short window analysis.

## □ Spectral decomposition is helpful because:

1. Unpredictable geology and whitened spectrum in a long window;
2. In short window analysis, local geology filters wavelet and overprints it in frequency domain.

## □ Some difficulties in spectral decomposition:

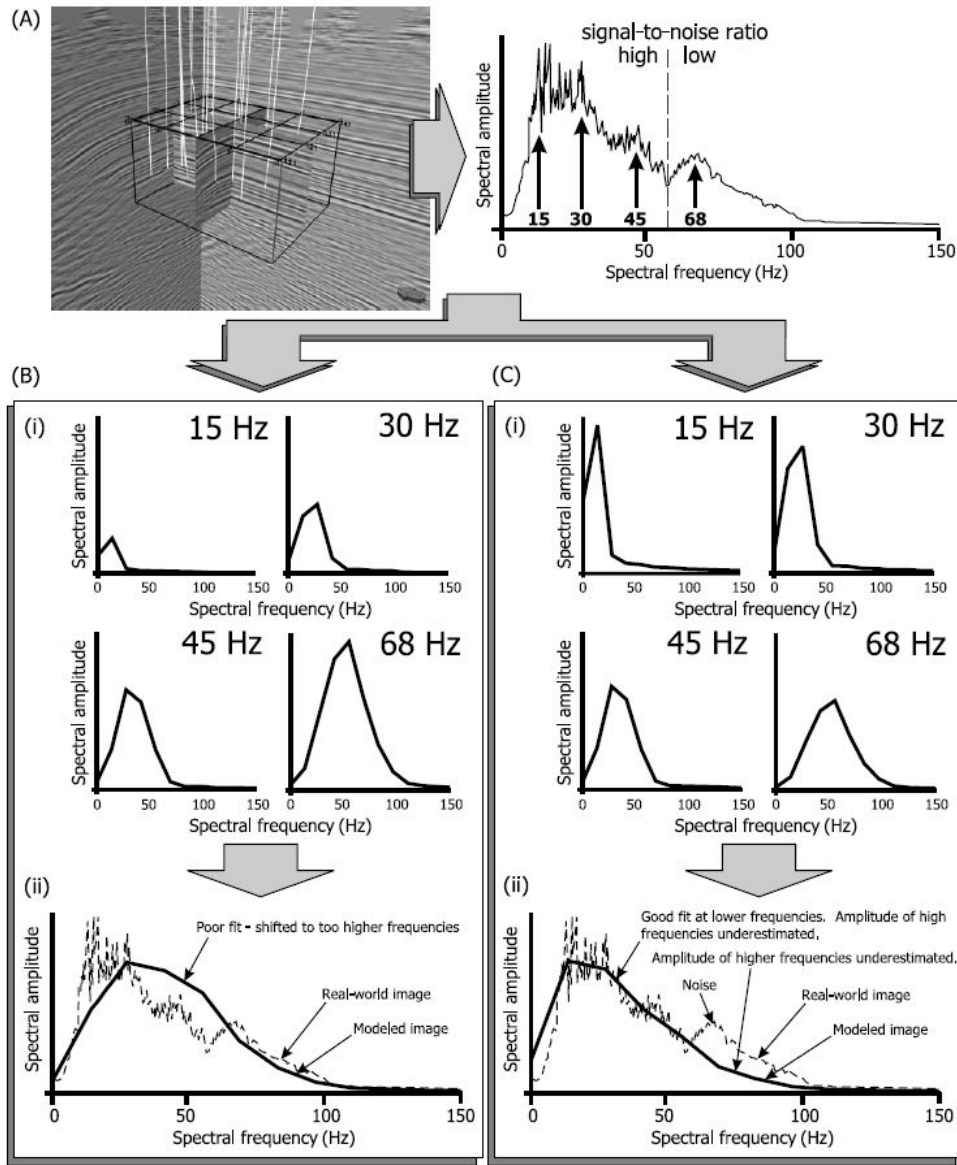
(Greg Partyka, James Gridley, and John Lopez, 1999)

1. Time-frequency resolution limit;
2. Residuals in “frequency gathers”.

(Chakraborty and Okaya, 1995)

(Chen, 2008)

# Spectral Recomposition



1. Manually select component frequencies;
2. Compute spectrum of each component;
3. Scale amplitude spectrum of each component;
4. Sum components up.

# Theory

Model:

$$d(f) \approx \sum_{i=1}^n a_i \Psi_i(m_i, f)$$

$d(f)$  is the spectrum of seismic data;

$a_i$  and  $m_i$  are the amplitude and peak frequency of the  $i$ -th Ricker component.

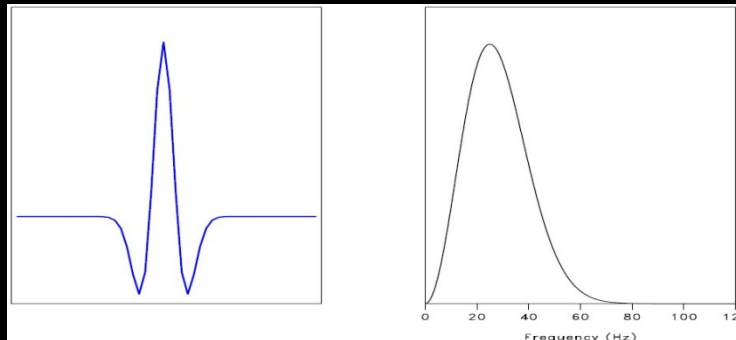
Ricker spectrum:

$$R(f) = a \Psi(m, f) = a \frac{f^2}{m^2} \exp\left(-\frac{f^2}{m^2}\right)$$

To estimate a seismic spectrum, we need:

$$\mathbf{a} = \{a_1, a_2, \dots, a_n\} \quad \text{and} \quad \mathbf{m} = \{m_1, m_2, \dots, m_n\}$$

Each component has its own amplitude and peak frequency terms.



# Numerical Method – Separable Nonlinear Least Squares

Let

$$r_j(\mathbf{a}, \mathbf{m}) = d(f_j) - \sum_{i=1}^n a_i(\mathbf{m}) \Psi_i(m_i, f_j)$$

Optimal least-squares estimation requires:

$$\min_{\mathbf{a}, \mathbf{m}} \|\mathbf{r}(\mathbf{a}, \mathbf{m})\|_2^2$$

Linear and nonlinear parts are solved *separately* by least squares method.

(Scolnik, 1972)

The variable projection algorithm has been used. Assuming  $\mathbf{m}$ , we have:

$$\mathbf{a} = \Psi(\mathbf{m})^\dagger \mathbf{d}$$

where

$\Psi(\mathbf{m})$  is the matrix composed of

$$\Psi_i(m_i, f_j)$$

(Golub & Pereyra, 1973)

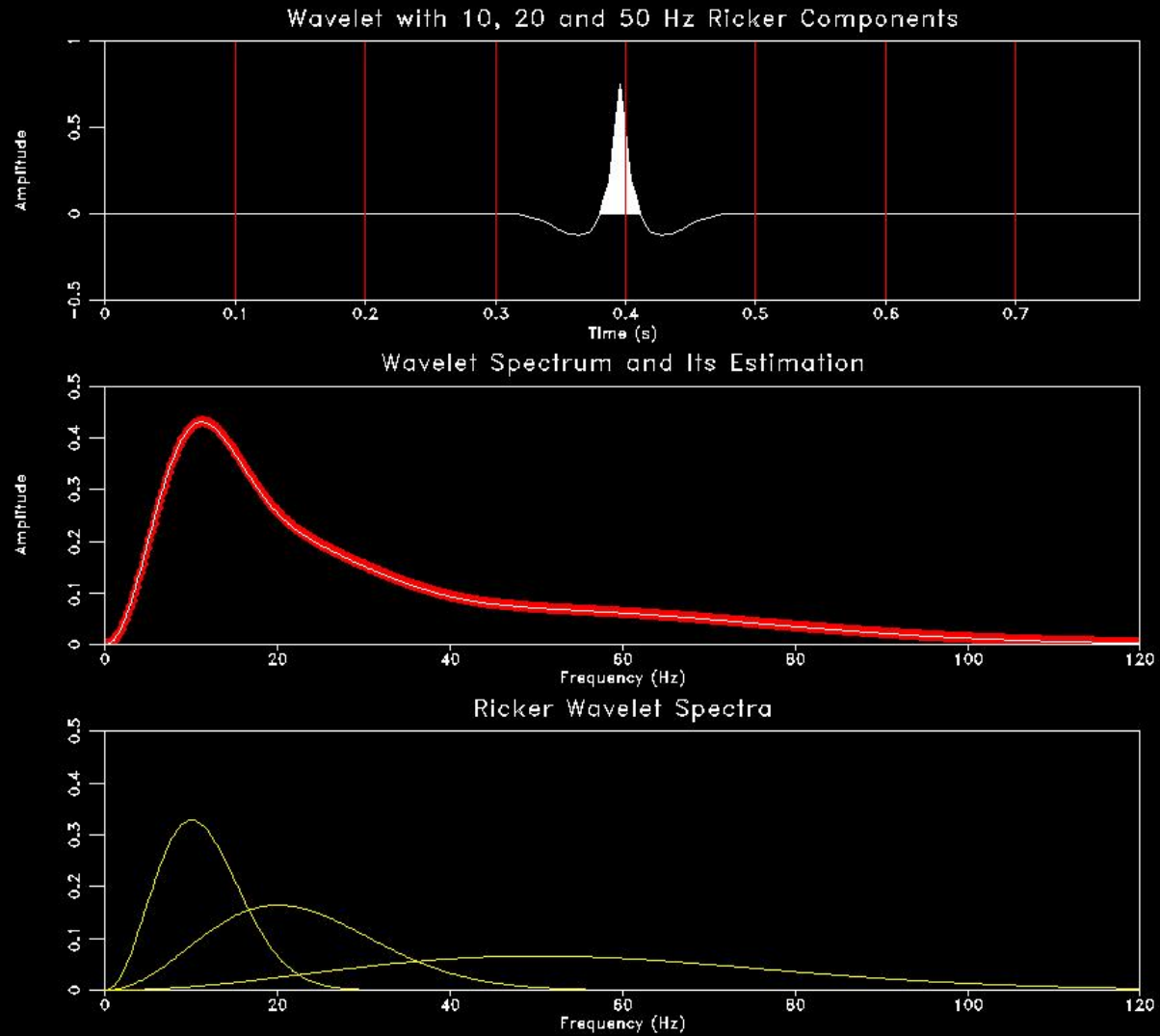
Having  $\mathbf{a}$  solved, we then need to solve

$$\min_{\mathbf{m}} \|\mathbf{d} - \Psi(\mathbf{m})\Psi(\mathbf{m})^\dagger \mathbf{d}\|_2^2$$

Gauss-Newton method has been used, hence

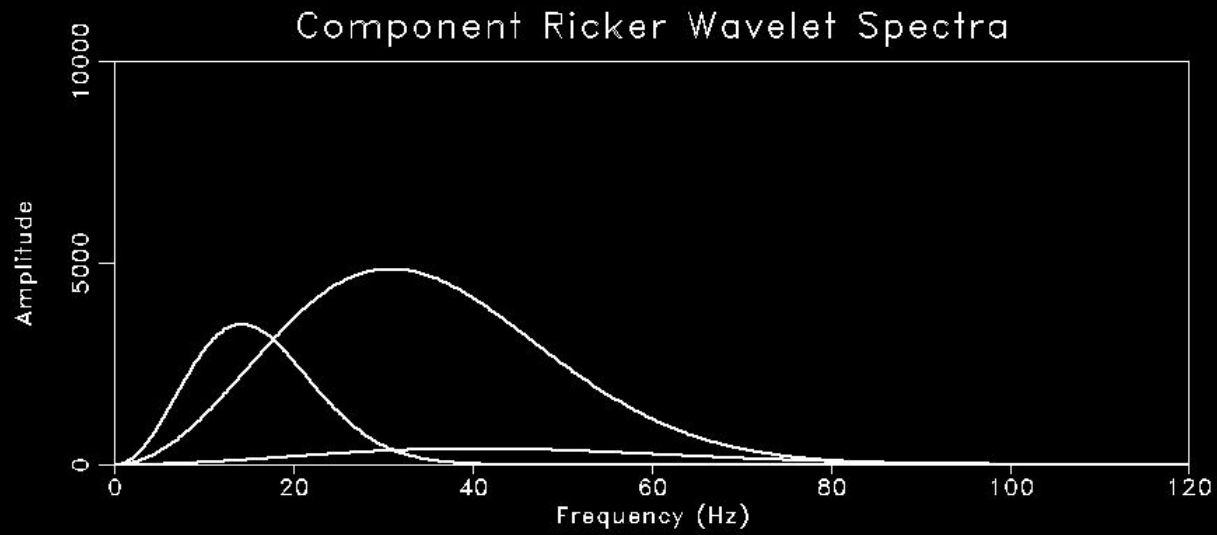
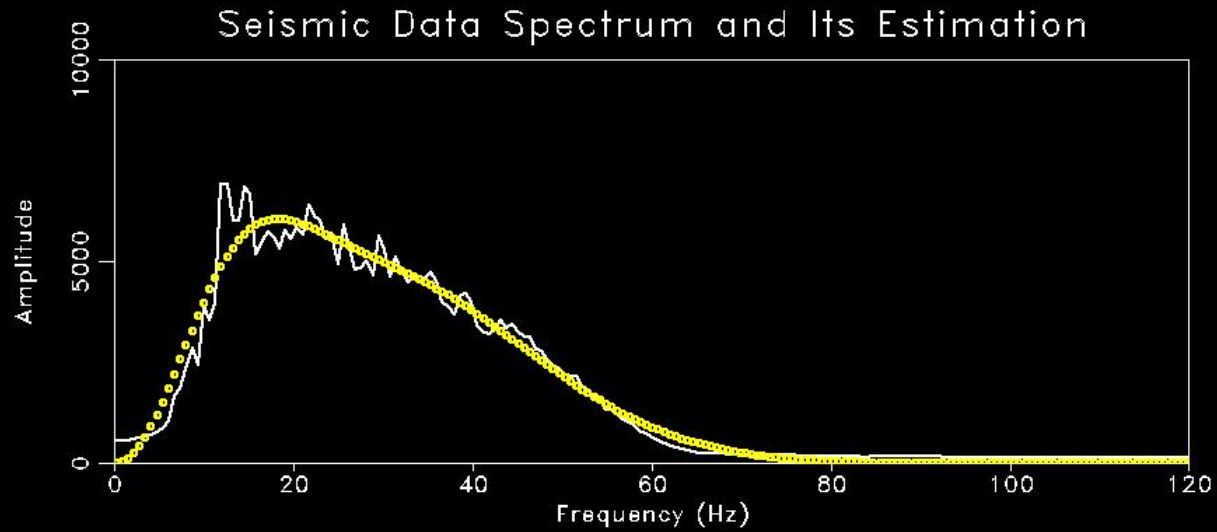
$$\begin{aligned} d(f_j) &\approx \sum_i r_j(m_i, f_j) + \sum_i \frac{\partial r_j}{\partial m_i} \Delta m_i \\ &\approx \sum_i a_i \Psi(m_i, f_j) + \sum_i [a_i' \Psi(m_i, f_j) + a_i \Psi'(m_i, f_j)] \Delta m_i \end{aligned}$$

# Spectral Recomposition – Synthetic Data

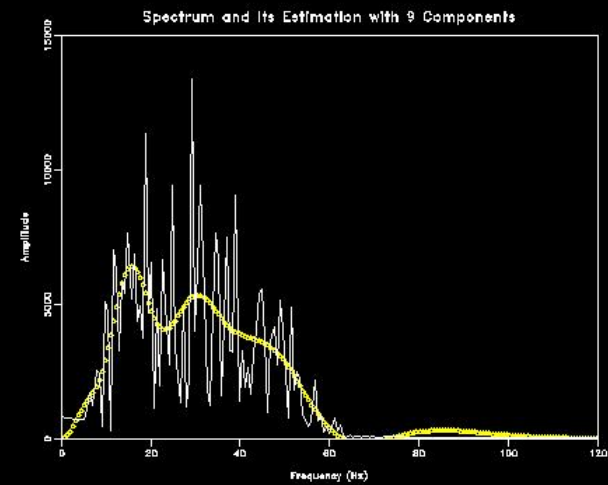
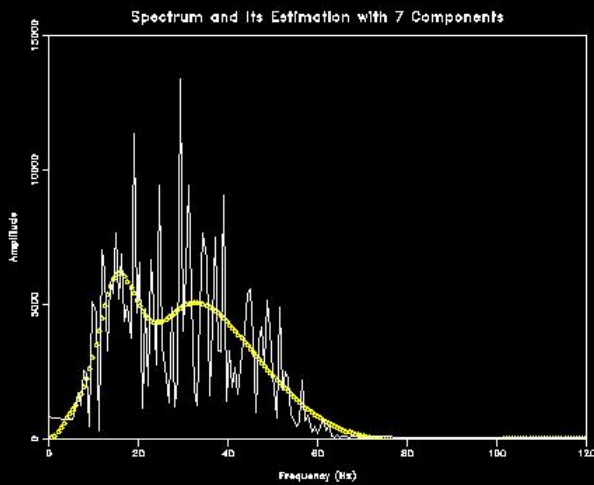
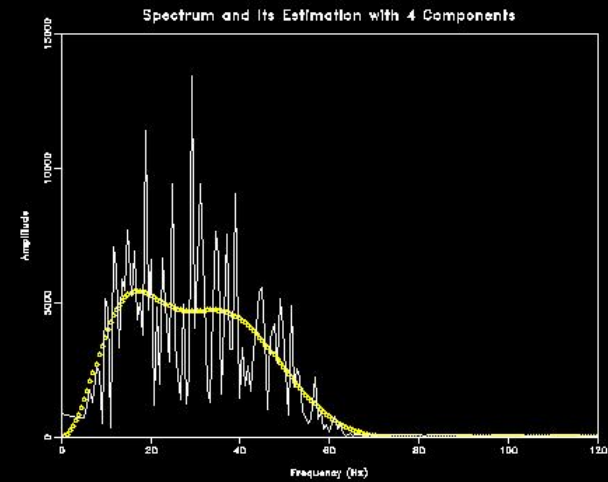
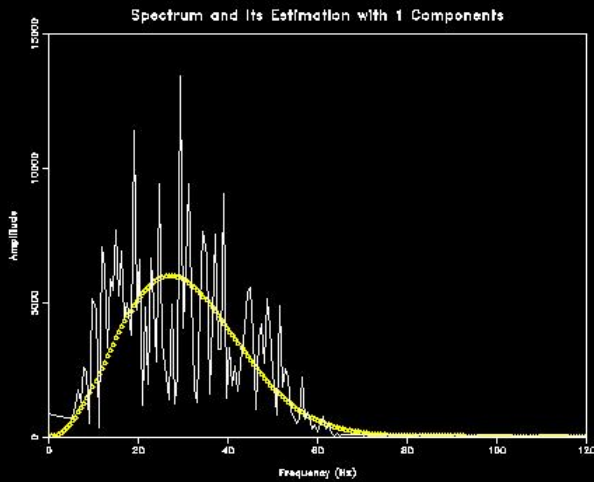




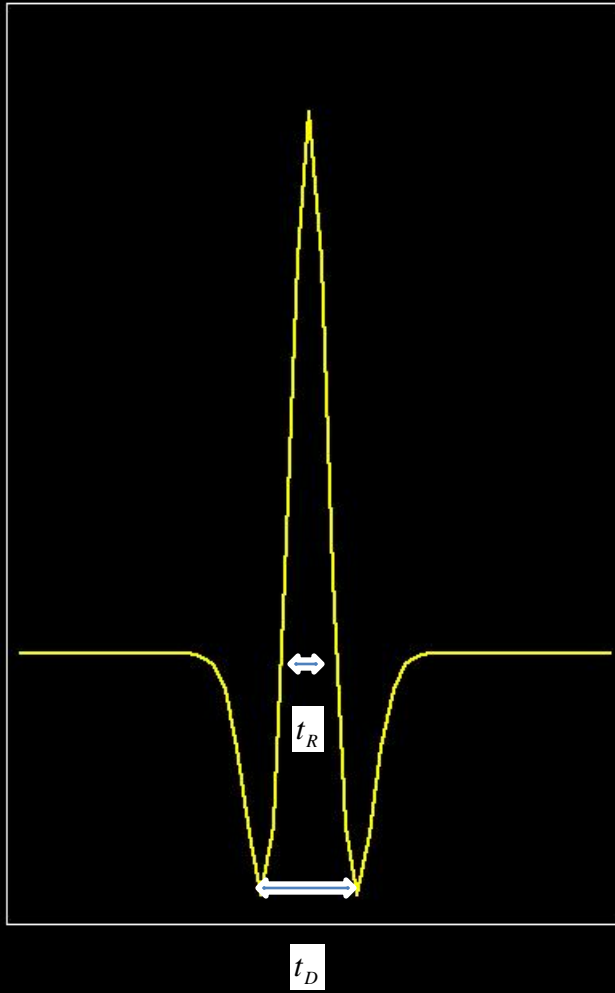
# Spectral Recomposition – Real Data Example



# Spectral Recomposition – Data Fitting Example

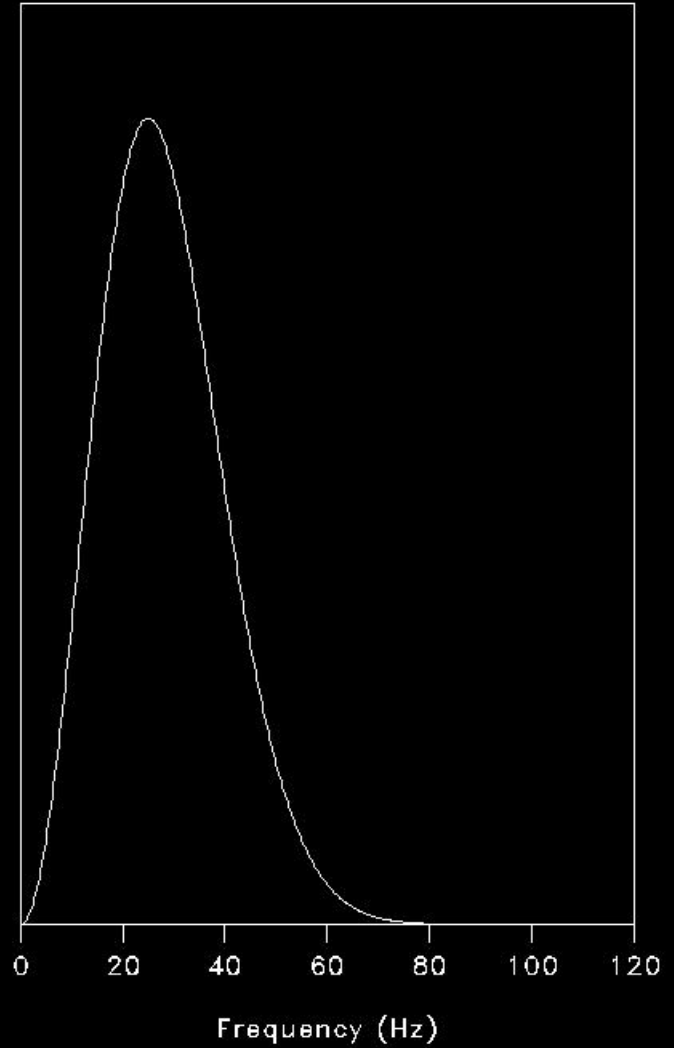


# Frequency Band Picking



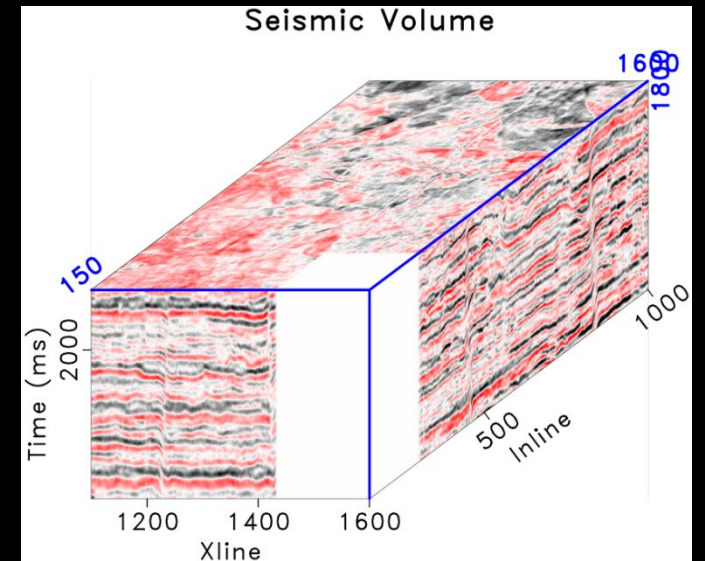
$$t_R = t_D / \sqrt{3}$$

$$t_D = \sqrt{6} / f_m \pi$$

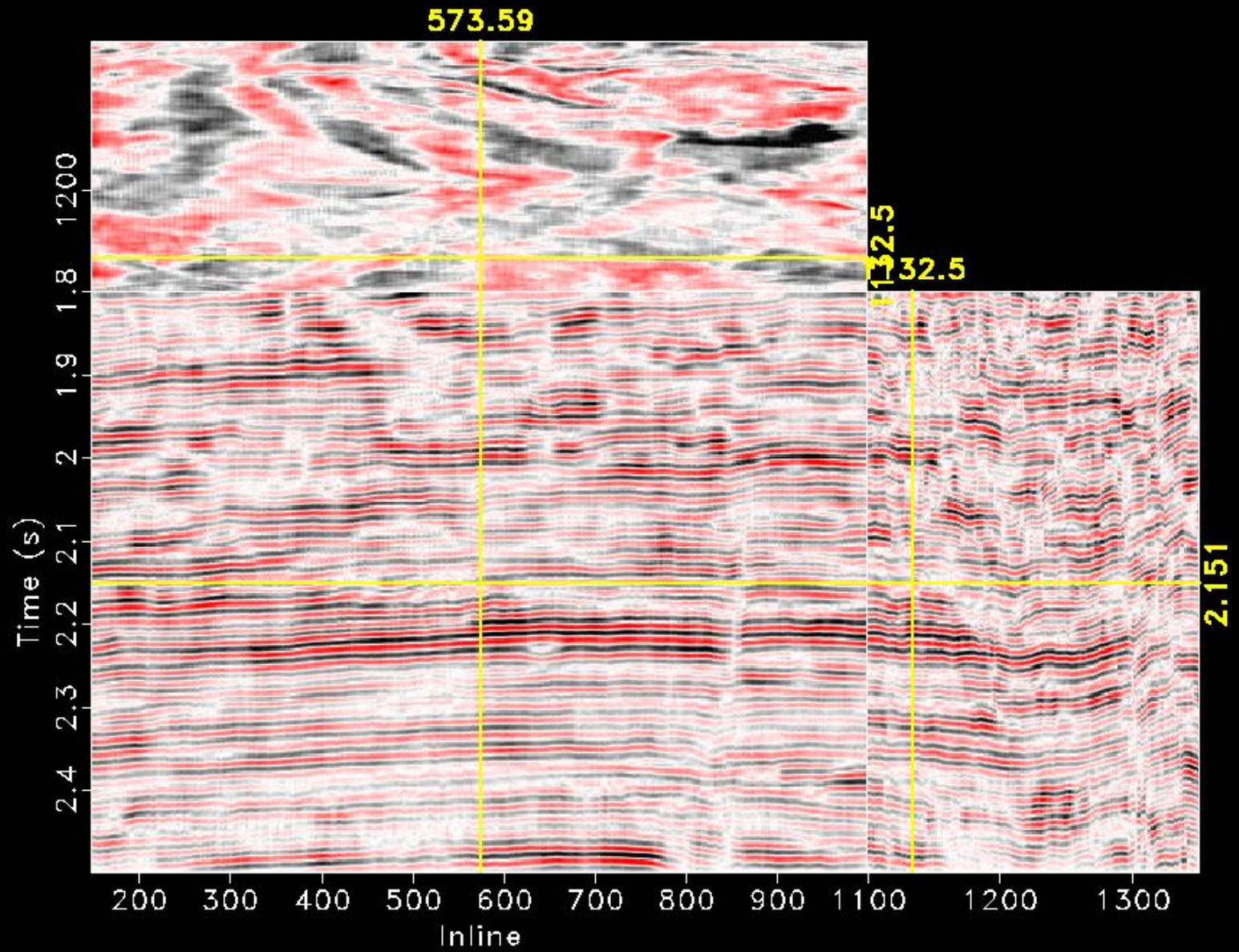


# Application of Spectral Recomposition Using SNLS

- ❑ Seismic image display
- ❑ Stratal slice imaging and RGB color blending
- ❑ Time-frequency analysis simulation

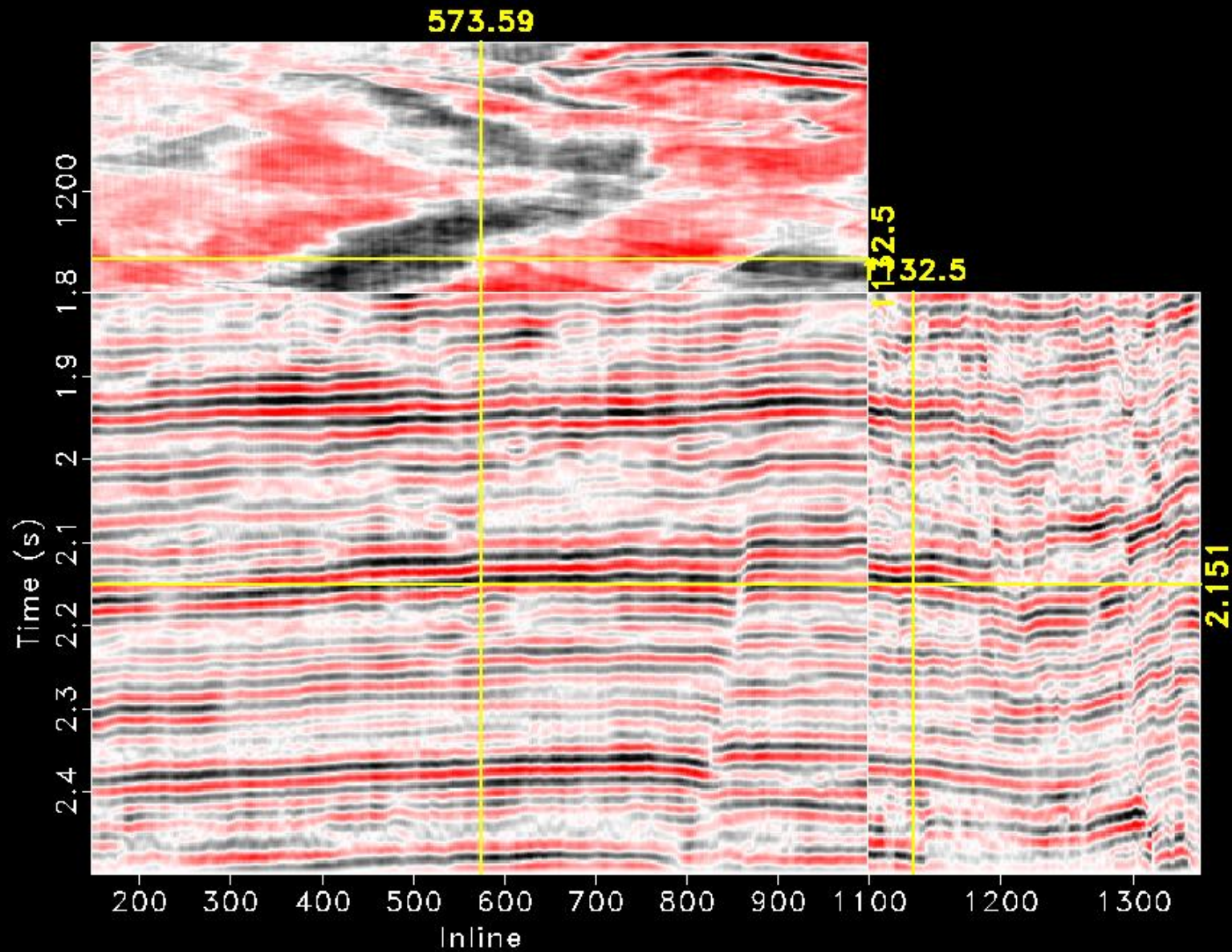


# Component Peak Frequency 30 Hz

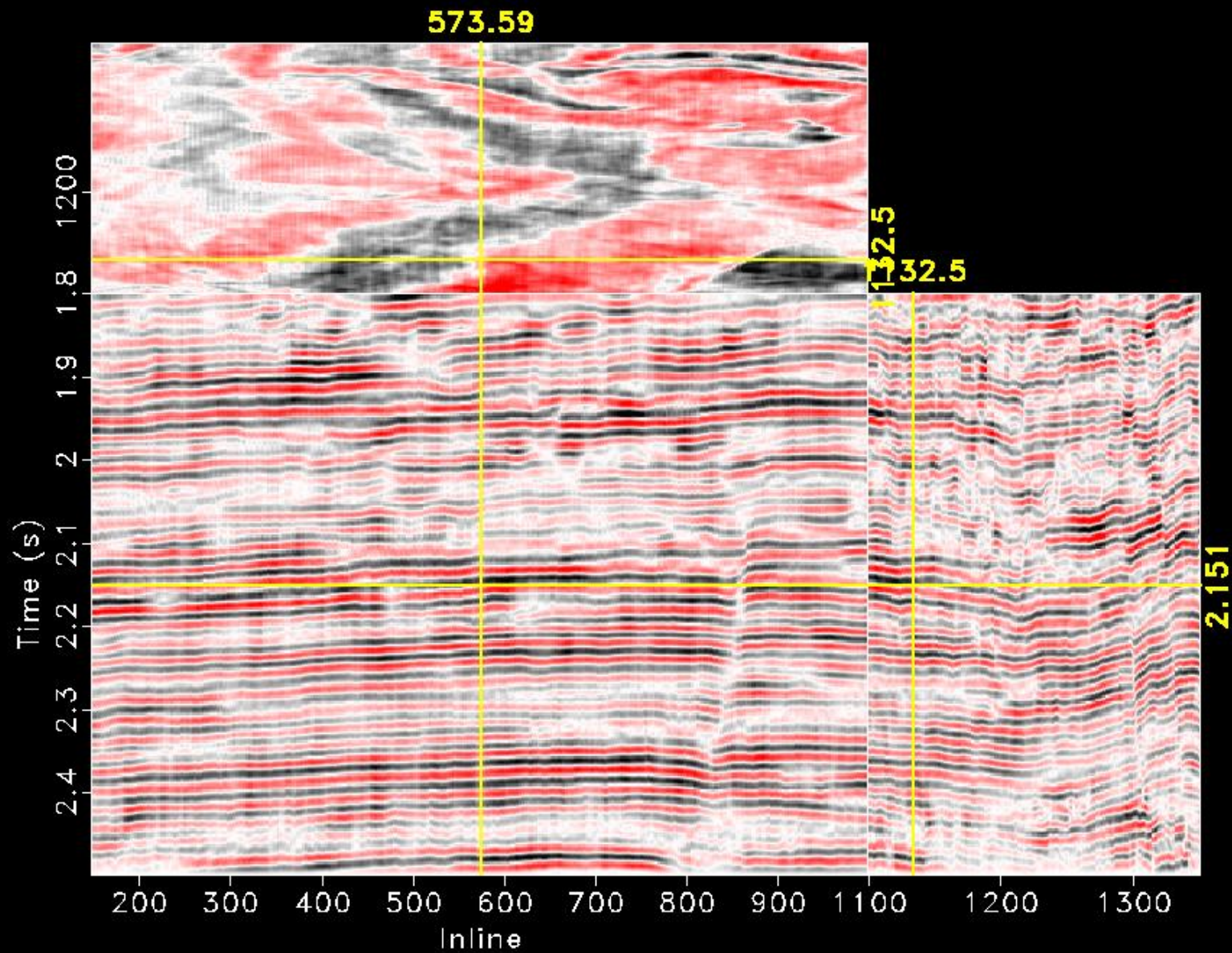




# Component Peak Frequency 17 Hz



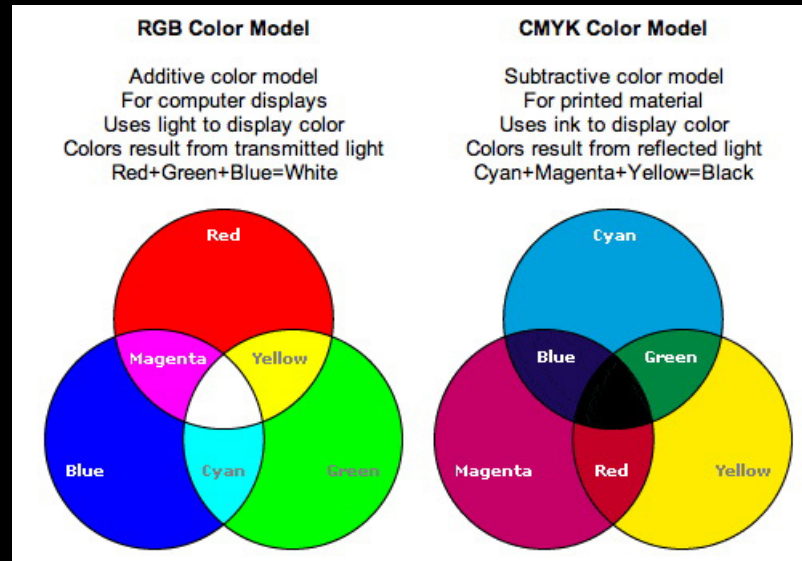
# Component Peak Frequency 21 Hz





# RGB Color Blending Plot

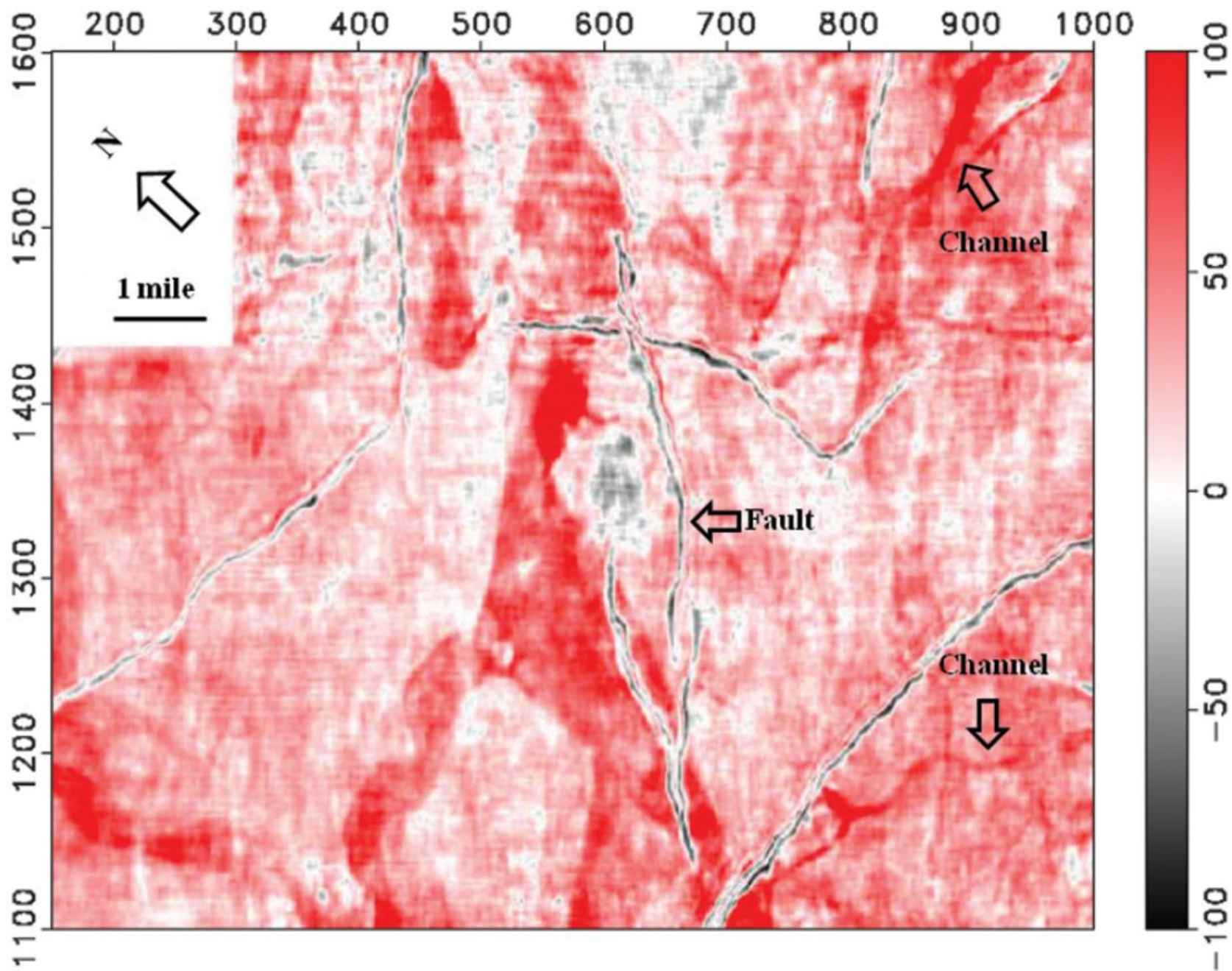
- RGB color model: an additive color model in which red, green, and blue are added together to produce a broad array of colors.



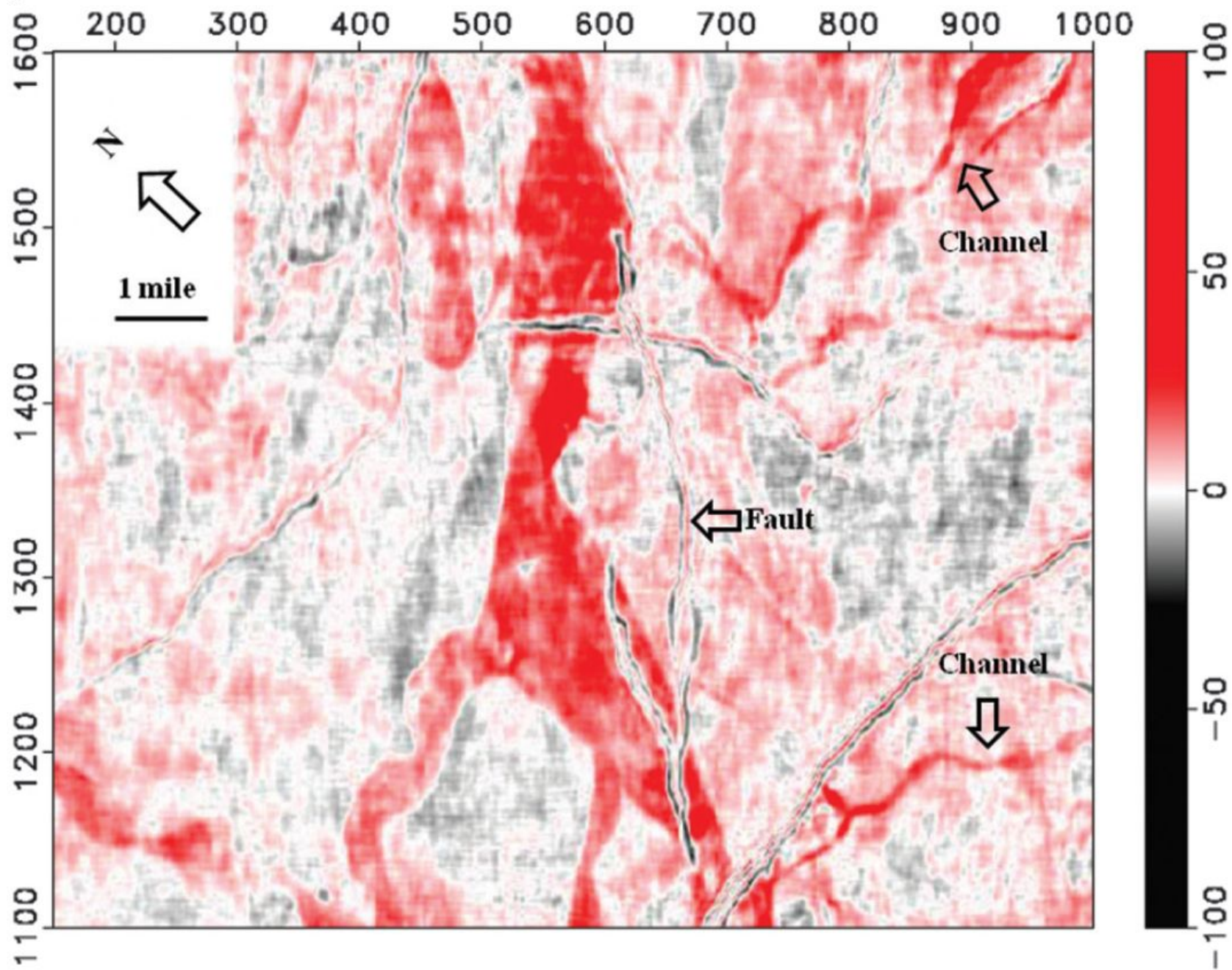
- Using color blending plot, we can visualize subtle geologic features
- Various color blending plots based on various types of seismic attributes



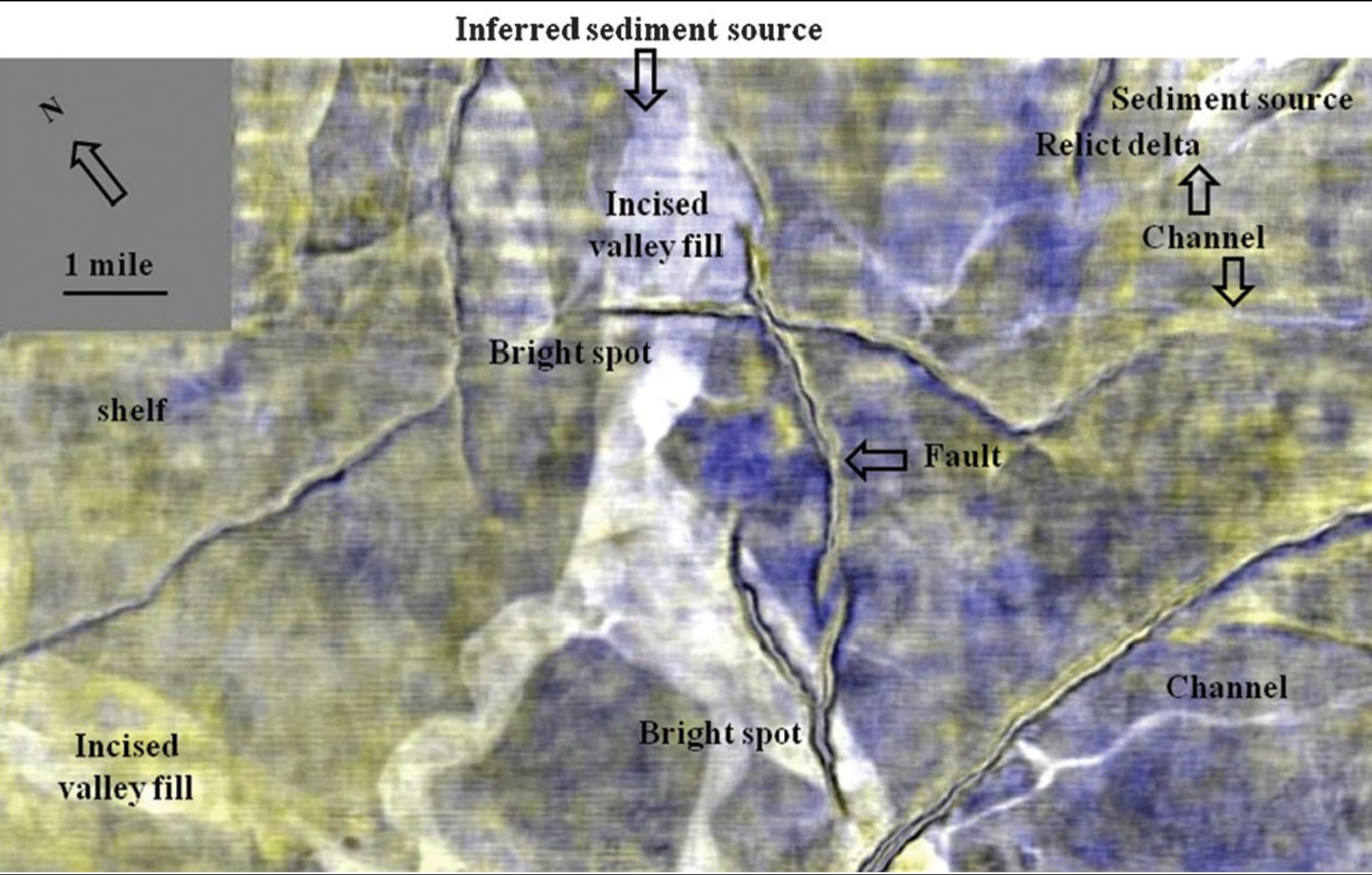
a)



b)







**Inferred sediment source**



**Sediment source**

**Relict delta**



**Incised  
valley fill**

**Channel**



**Bright spot**



**Fault**

**shelf**

**Channel**

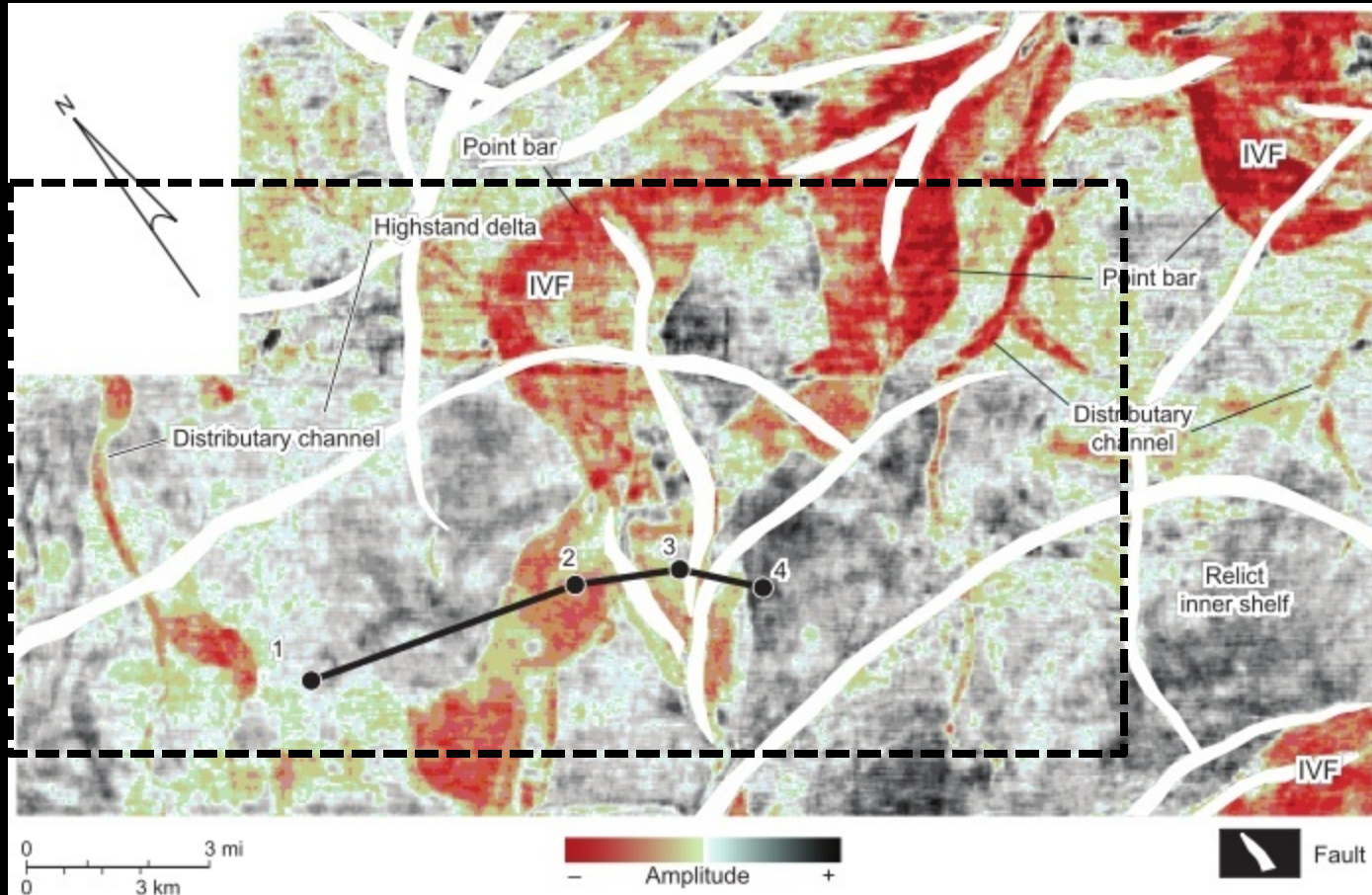
**Bright spot**

**Incised  
valley fill**



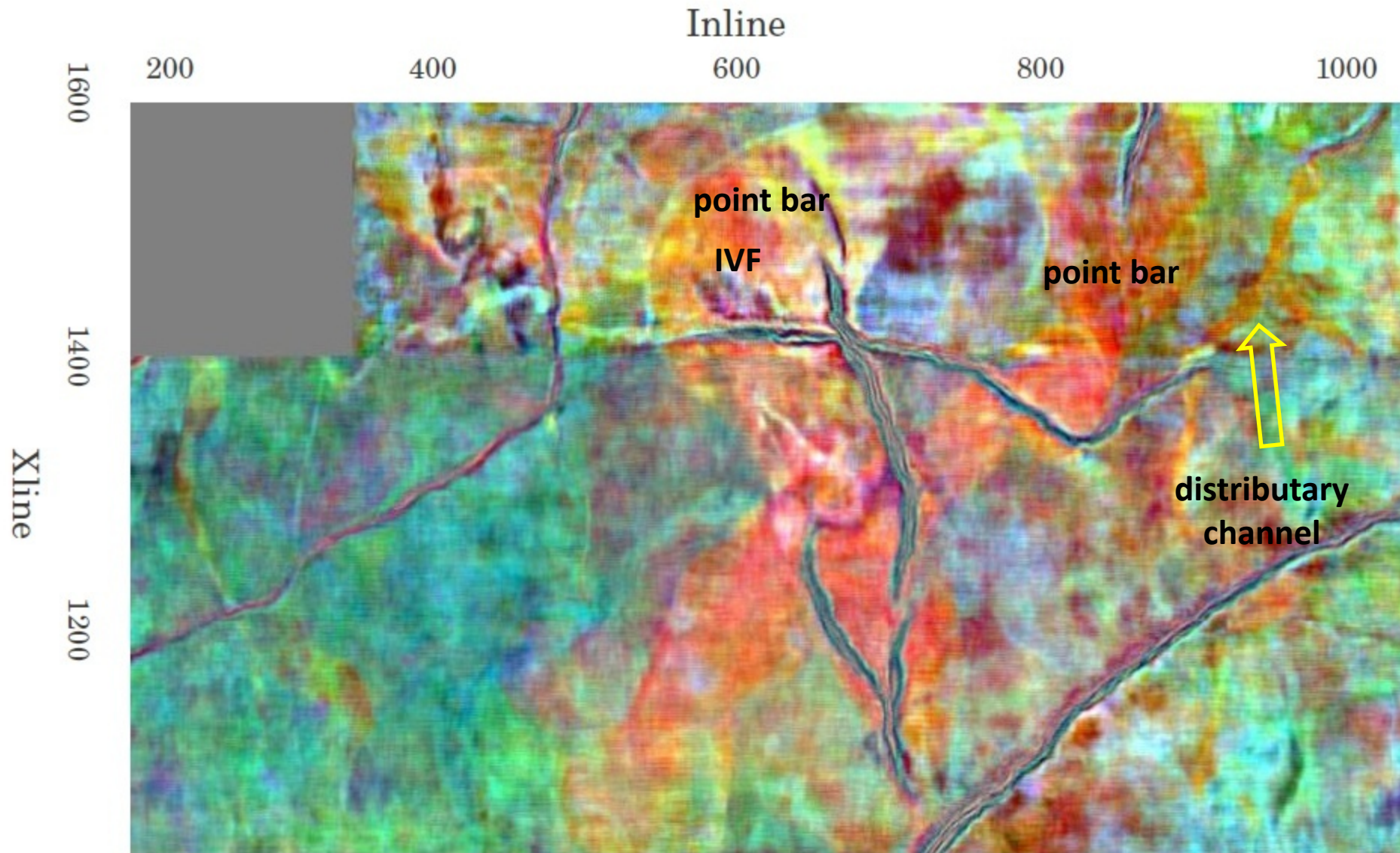
**1 mile**

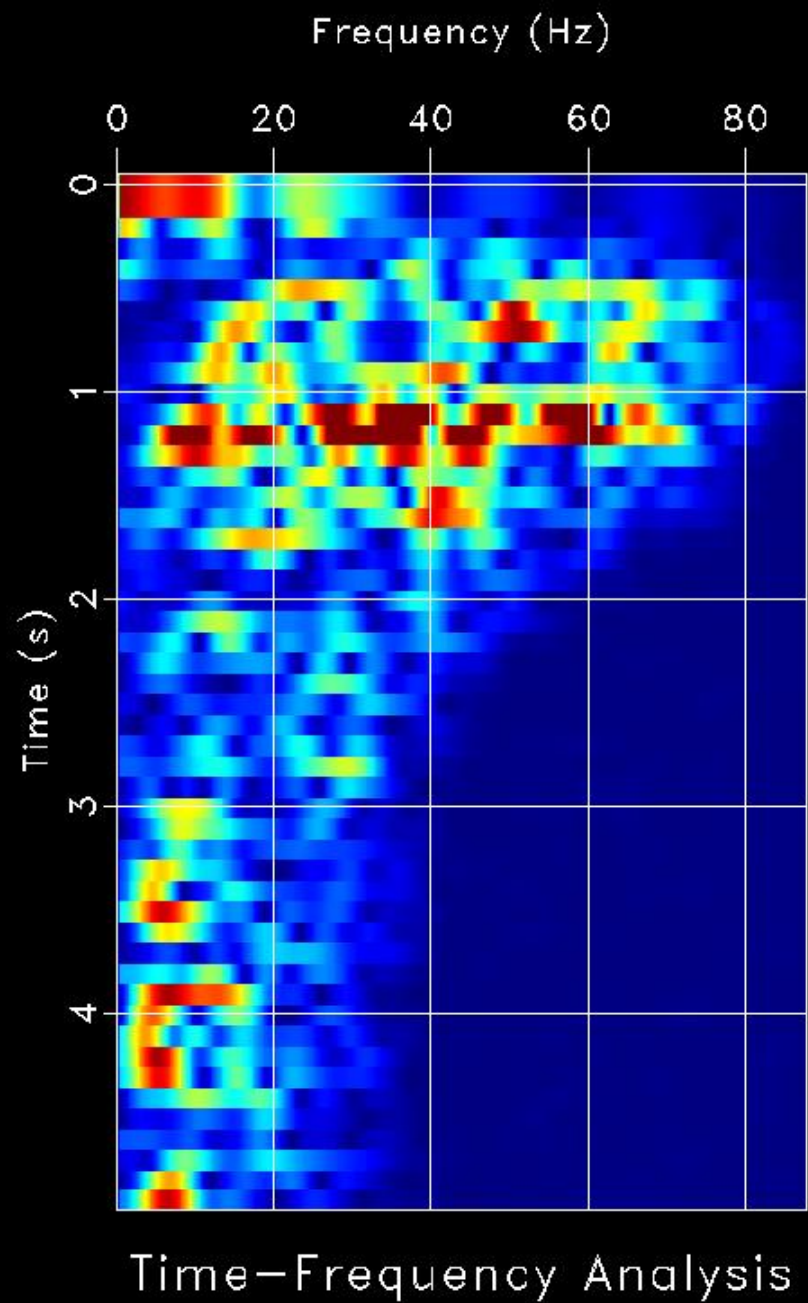
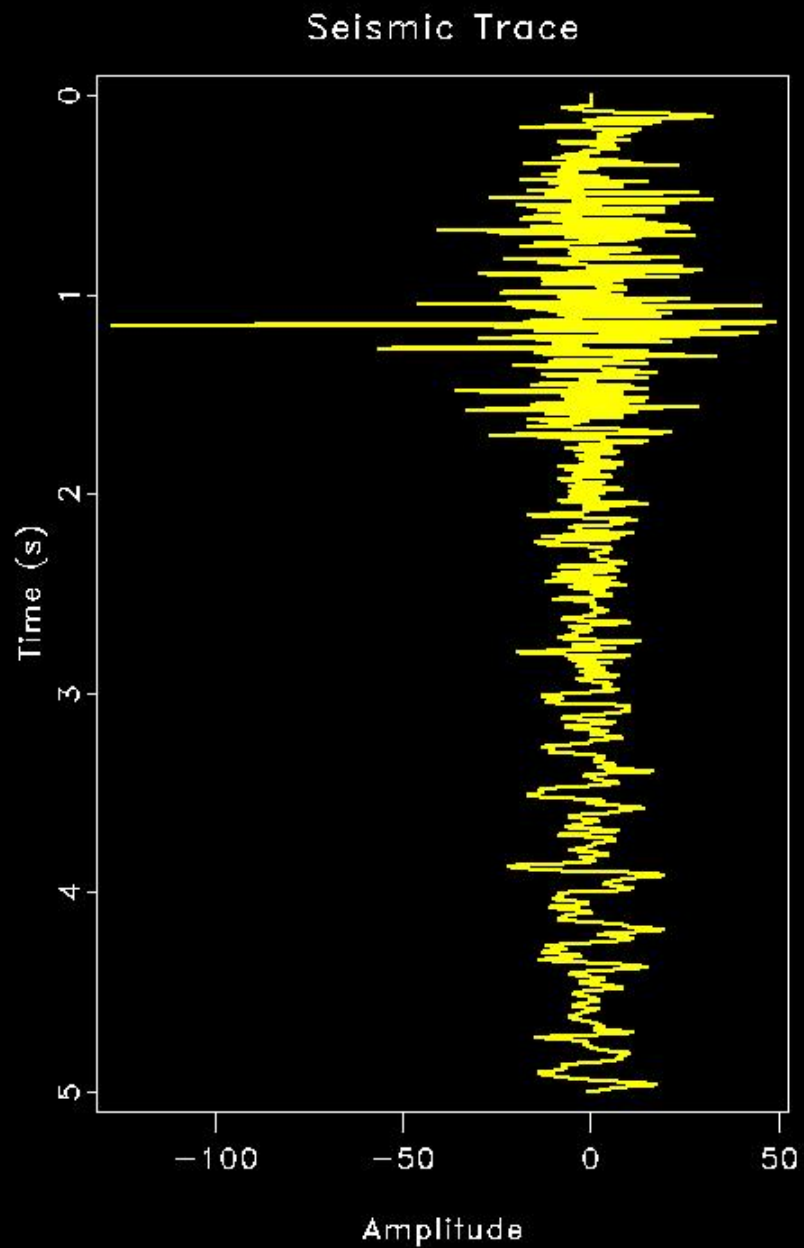
# Stratal Slice



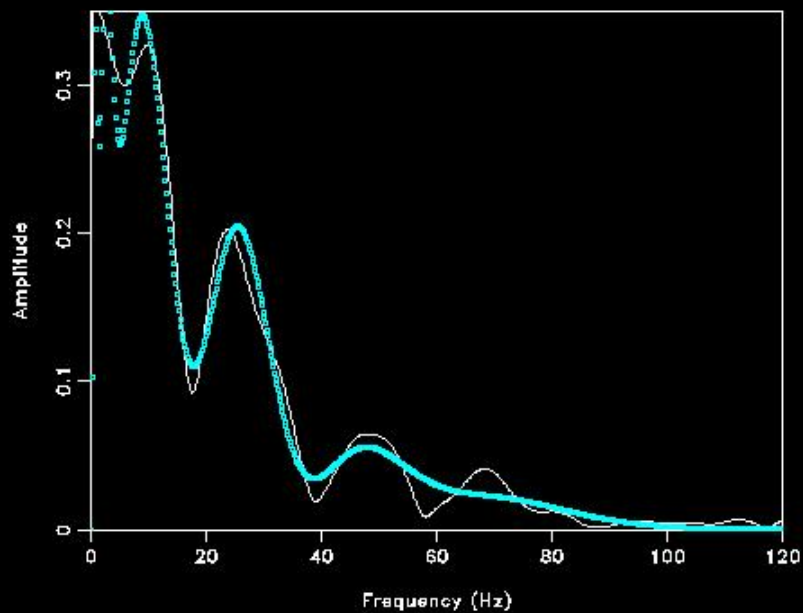


# RGB Color Blending Plot with Significant Components

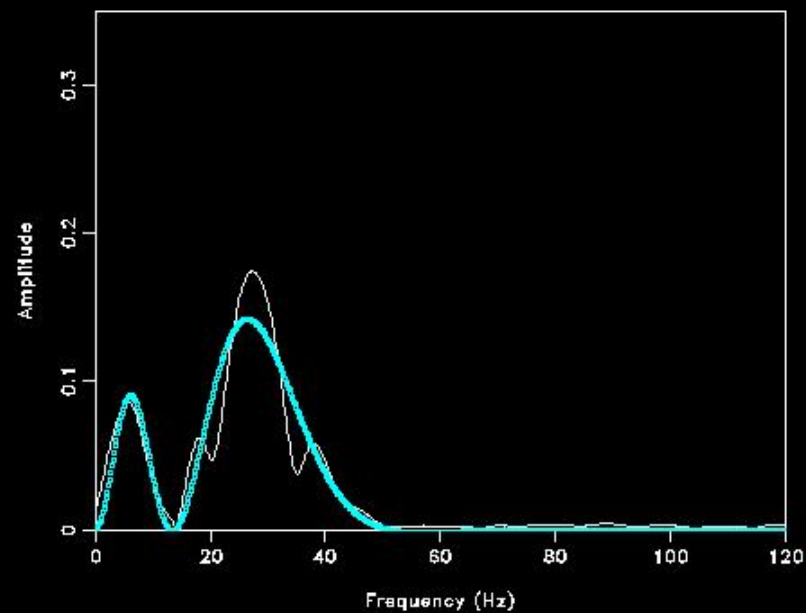




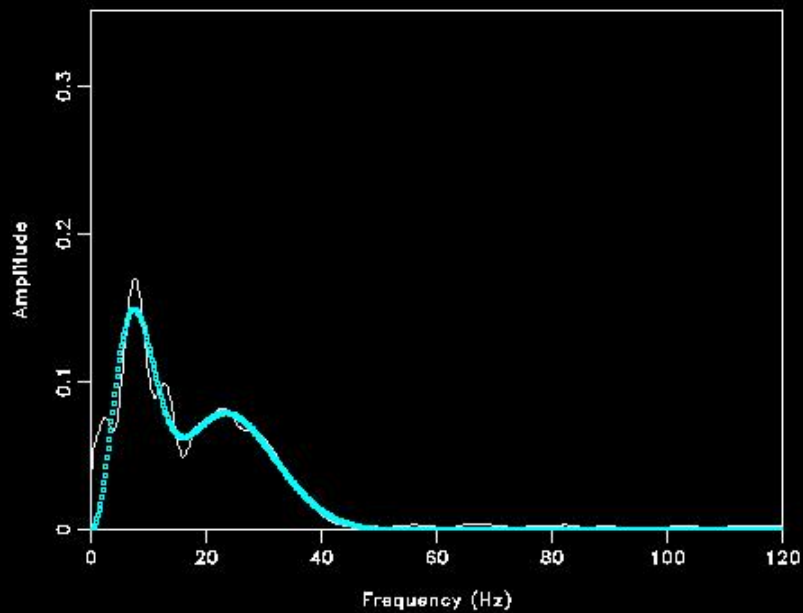
Spectrum of 0 Second(s) Depth



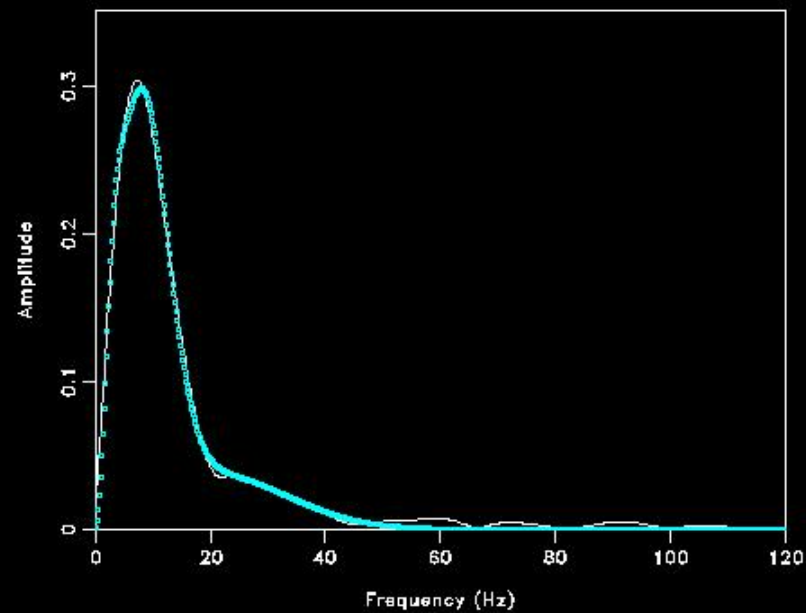
Spectrum of 2 Second(s) Depth



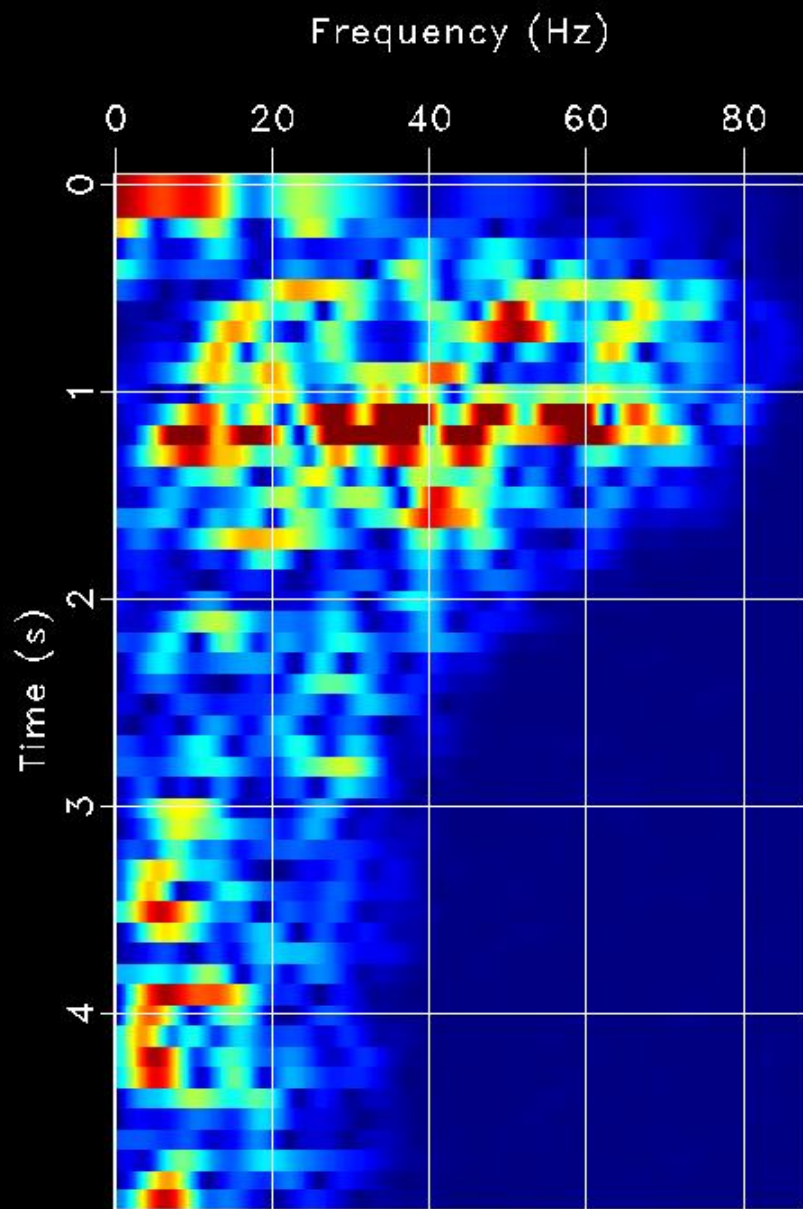
Spectrum of 3 Second(s) Depth



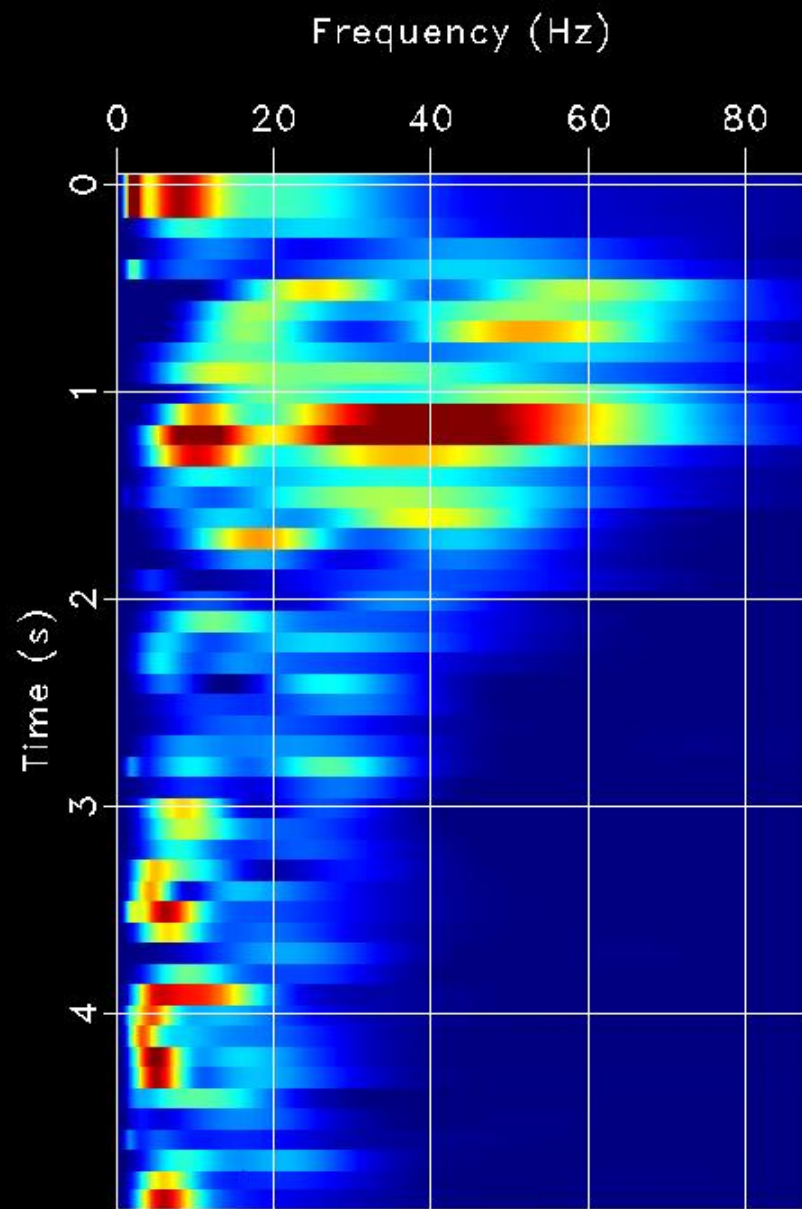
Spectrum of 5 Second(s) Depth







Time-Frequency Analysis



Spectral Recomposition



## Summary

- ❑ Spectral recomposition as a new approach of spectral analysis
  - ❑ extracts significant component frequencies and their amplitudes
  - ❑ reconstructs seismic spectrum accurately and efficiently
  - ❑ improves seismic display, color blending plot and t-f analysis
  - ❑ can be used in inversion, reservoir characterization, etc.
- ❑ SNLS in spectral recomposition
  - ❑ converges to local minimum quickly
  - ❑ allows interpreter to choose number of components in estimation

Golub, G.H., and V. Pereyra, 1973, The differentiation of pseudoinverses and nonlinear least squares problems whose variables separate: *SIAM Journal on Numerical Analysis*, v. 10, p. 413-432.

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