Modeling Prospect Dependencies with Bayesian Networks*

Gabriele Martinelli¹

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¹Department of Mathematical Sciences, NTNU, Norwegian University of Science and Technology, Trondheim, Norway (gabriele.martinelli@math.ntnu.no)

Abstract

In recent years, great interest has been devoted to the evaluation of prospect dependencies. Here, we look at the use of Bayesian networks based on trap, source, and reservoir probabilities as a tool for analyzing a set of prospects. With such networks in place, we can easily run what-if drilling scenarios to determine drilling sequences. We exemplify this by finding the minimum number of dry wells to drill before abandoning an area.

In oil exploration, the probability of success for a prospect is often split into three independent factors: reservoir, trap, and source. These represent the presence of reservoir rock, a closed trap, and oil migrating into the reservoir, respectively. We model dependencies between prospects by using one Bayesian network for each of these factors.

A Bayesian network is a powerful, yet simple tool for representing dependencies. With one network representing the geological dependencies for reservoir rock, another traps and a third one sources and possible flow paths, it is evident that the networks mirror physical dependencies and that the nodes have physical interpretation. The two first networks use binary success/failure nodes, whereas the source nodes may have four states if both oil and gas are modeled (dry, oil, gas, oil and gas). This discrete state situation fits nicely into the Bayesian network framework.

With the help of a team of experts, we have created such networks. With these networks established, it is easy to evaluate the changes in probability and economic viability for different prospects given new well data. The main strength of this is to feed the model with hypothetical well data, and use it to compute values of information and plan drilling sequences.

Using networks based on a real case, we show how a drilling plan can be created. The setting is that we want to drill as few dry wells as possible before abandoning the area. With a full model for dependencies, it is easy to evaluate the economic viability of the remaining prospects given a set of dry wells, and by running through all small subsets, we find the optimal solution.

²NR, Norwegian Computing Center, Oslo, Norway.

We show that Bayesian networks are a powerful tool, both for analyzing and modeling the dependencies between prospects in an area. With such a model in place, it is easy and fast to update probabilities and expected value of prospects as new data become available. This is useful for well planning.

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Modeling Prospect Dependencies with Bayesian Networks

Gabriele Martinelli Norwegian University of Science and Technology, Trondheim, Norway

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Joint work with Jo Eidsvik, Ragnar Hauge, Maren Drange Førland



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- 3 Exploratory analysis
- Optimal Exploration

Motivations and goals

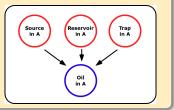
- How do prospect dependencies affect analysis of a geologically appealing area? [Van Wees et al, 2008], [Cunningham and Begg, 2008].
- Find the drilling sequence maximizing criteria of interest [Bickel and Smith, 2006].
- Formulate the problem of Vol [Bratvold et al., 2009], [Eidsvik et al., 2008] in the BN context and propose interpretation of the results

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Model framework:

Three main components are required for oil and gas to accumulate in sufficient quantities to be worth producing: source, reservoir, and trap.

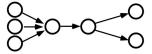


Bayesian Networks

Bayesian Network

A Bayesian network is a graphical model for probabilistic relationships among a set of variables.

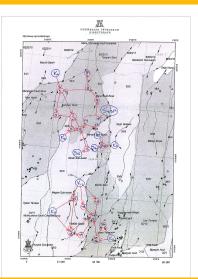
Example:

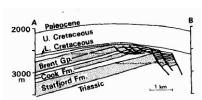


BN are directed acyclic graphs. Nodes represent variables, edges encode conditional dependencies between the variables.

Over the last decade, the Bayesian network has become a popular representation for encoding uncertain knowledge in expert systems.

The North Sea case study





- Several sites (nodes) have been chosen,
- Discrete model ⇒ three possible states for each node (*dry, gas* or *oil*).
- Three different models for source, reservoir and trap ⇒ We focus on the source model.

Encoding the geological information in the BN

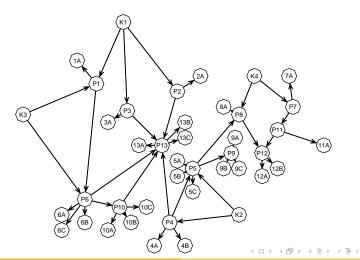
Qualitative part:

- List of nodes: either sites chosen for potential drilling or areas where the HC formation developed
- Possible outcomes at any segment
- Map of possible migration paths (edges)

Quantitative part:

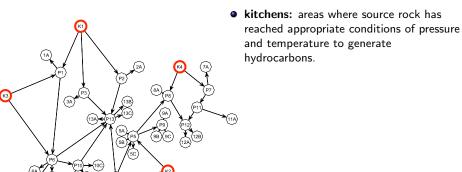
- Conditional probabilities: expert belief
- Expected a priori volumes
- Expected values of oil and gas and operational costs

The Bayesian Network of our case study



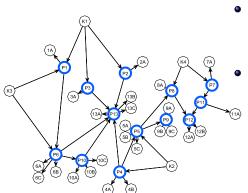
The nodes of the network

The model includes 3 possible kinds of nodes:





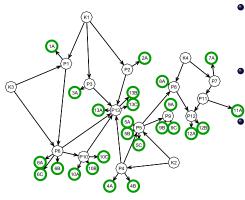
The nodes of the network



The model includes 3 possible kinds of nodes:

- kitchens: areas where source rock has reached appropriate conditions of pressure and temperature to generate hydrocarbons.
 - prospects: key-nodes of the network.
 Through them we can define the spatial relationships that we need.

The nodes of the network



The model includes 3 possible kinds of nodes:

- kitchens: areas where source rock has reached appropriate conditions of pressure and temperature to generate hydrocarbons.
 - prospects: key-nodes of the network. Through them we can define the spatial relationships that we need.
 - segments: bottom nodes of our network. They correspond to physical 3D locations. Different segments are distinguished by:
 - Depth
 - Latitude and longitude
 - Relative position wrt a geological element (fault,...)

Vi	$P(v_j = \text{Dry} v_i)$	$P(v_j = \operatorname{Gas} v_i)$	$P(v_j = \text{Oil} v_i)$
Dry	X	X	X
Gas	×	×	×
Oil	X	x	×

Vi	$P(v_j = \text{Dry} v_i)$	$P(v_j = \operatorname{Gas} v_i)$	$P(v_j = \mathrm{Oil} v_i)$
Dry	X	X	×
Gas	×	×	×
Oil	X	X	×

- Physical constraints
- Few parameters: $v_{ij}^{HC} = P(HC \text{ in } j|HC \text{ in } i)$, and $v_{ii}^{G} = P(v_{j} = \text{gas}|HC \text{ in } j \land HC \text{ in } i)$

Vi	$P(v_j = \text{Dry} v_i)$	$P(v_j = \operatorname{Gas} v_i)$	$P(v_j = \mathrm{Oil} v_i)$
Dry	1	0	0
Gas	$1-v_{ij}^{HC}$	$v_{ij}^{HC} * v_{ij}^G$	$v_{ij}^{HC}*(1-v_{ij}^G)$
Oil	$1-v_{ij}^{HC}$	0	v_{ij}^{HC}

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1 The rules for the gas and oil flows:

Vi	$P(v_j = \text{Dry} v_i)$	$P(v_j = \operatorname{Gas} v_i)$	$P(v_j = \text{Oil} v_i)$
Dry	1	0	0
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Parents with different states:

Vi	$P(v_j = \text{Dry} v_i)$	$P(v_j = \operatorname{Gas} v_i)$	$P(v_j = \text{Oil} v_i)$
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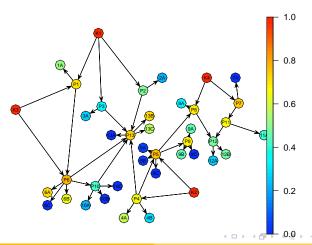


- Parents with different states:
 - Gas is lighter than oil. It forces itself into the pockets and squeezes the oil out of the trap. Assumptions of abundance and time are met.



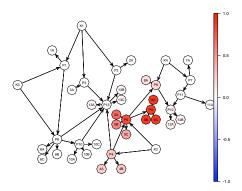
Marginal distribution of state $\{gas\}$

$$P(v_j = gas) \ \forall \ j \in \{1, \dots, 42\}$$



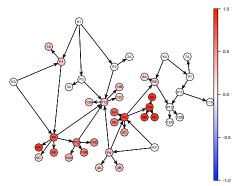
Single-site evidence

- What if we drill at segment i and get **evidence** v_i .
- We evaluate $P(v_i|v_i) P(v_j) \ \forall \ i \in \{1, \dots, 42\}$
- In the example, $\{9A\} = dry$



Multiple-site evidence

- What if we drill at segments i and j and get the **evidence** v_i, v_j .
- We evaluate $P(v_k|v_i,v_j) P(v_k) \ \forall \ k \in \{1,\ldots,42\}$
- In the example, $\{\{9A\} = dry, \{6A\} = dry\}$



Choice of criterion

The optimal decision strategy depends on the choice of the criterion, and by the purpose that we want to achieve, whether it is a sequential strategy [Bickel and Smith, 2006] or a simultaneous one.

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Our criteria:

- Which is the best combination of segments in order to maximize the total revenues?
- Which are the best segments to drill in order to give us the maximum confidence that the area is dry?

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Our criteria:

- Which is the best combination of segments in order to maximize the total revenues?
- Which are the best segments to drill in order to give us the maximum confidence that the area is dry?
- Value of Information (Vol) ⇒ [Bratvold et al., 2009] and [Bhattacharjya et al., 2010]
- ⇒ Abandoned Revenue (AR)

Technical details

For each segment, we have following data:

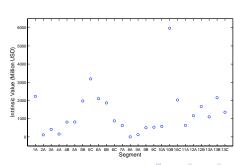
- Expected gas and oil volumes
- Assumed gas and oil values
- Fixed costs (includes the infrastructures and the well costs)
- Variable cost, proportional to the expected volume of gas and oil (includes the operation and the maintenance costs)

Technical details

These quantities allow us to compute:

- PRO_i: Partial Revenues for Oil, associated with segment i
- PRG_i: Partial Revenues for Gas, associated with segment i
- EFC: Exploratory Fixed Costs
- PFC: Prospect Fixed Costs

Intrinsic Value





The Value of Information

Idea:

- Select all the possible combinations of the segments of size p.
- Compute all the possible combinations of evidence (3^p), their prior probability of occurrence, and the conditional for the other segments.
- Include in the expected revenues with evidence, the segments having a balance between costs and revenues times the probability of HC higher than a fixed threshold (pre-posterior value).
- Find the Vol by subtracting the expected revenues without evidence

$$\mathrm{ER}(i) = \sum_{\mathrm{evidence}\ j} \left[\sum_{\mathrm{prospect}\ k} \max\{\mathrm{Rev}_{kj} - \mathrm{PFC}, 0\} \right] P(v_i = j),$$

where

$$\operatorname{Rev}_{kj} = \sum_{\text{segment } l \in k} \Big\{ \operatorname{PRO}_l * P(v_l = oil | v_i = j) + \operatorname{PRG}_l * P(v_l = gas | v_i = j) - \operatorname{EFC} \Big\}.$$

The Value of Information

Idea:

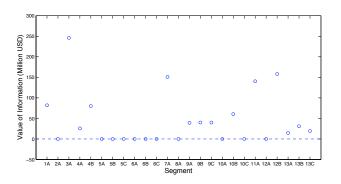
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- Find the Vol by subtracting the expected revenues without evidence

$$Vol(i) = ER(i) - \sum_{\text{prospect } k} \max\{\text{Rev}_k - \text{PFC}, 0\},$$

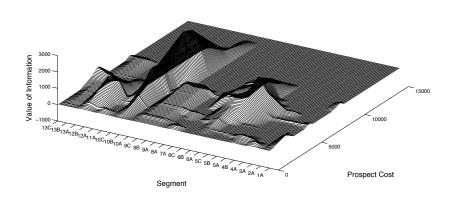
where

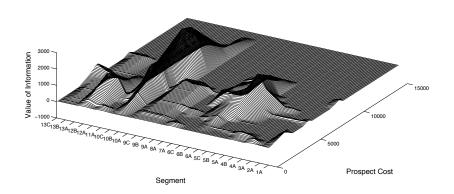
$$\operatorname{Rev}_k = \sum_{\text{segment } l \in k} \left\{ \operatorname{PRO}_l * P(v_l = oil) + \operatorname{PRG}_l * P(v_l = gas) - \operatorname{EFC} \right\}.$$

The Value of Information, p = 1



- Little correlation between the intrinsic values and the Vol
- A particular segment has a high Vol if its impact is able to change the decision that we would make





- Similar behavior for all segments: Vol increases, then decreases.
- Vol is not unimodal.
- Continuity of behavior among segments belonging to the same prospect.



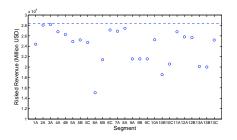
Idea:

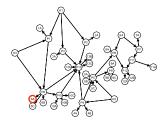
- Select segments that, if dry, give the maximum confidence about the scarce appealing of the area.
- Increase the dimension p, in order to find the joint best combination of segments

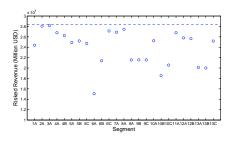
$$AR(i) = \sum_{\text{prospect } k} \max\{\text{Rev}_k - \text{PFC}, 0\},$$

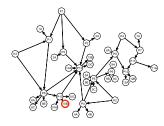
where

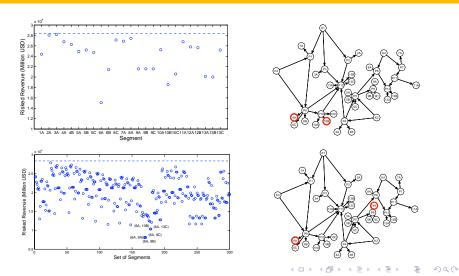
$$\operatorname{Rev}_k = \sum_{\text{segment } l \in k} \left\{ \operatorname{PRO}_l * P(v_l = oil | v_i = dry) + \operatorname{PRG}_l * P(v_l = gas | v_i = dry) - EFC \right\}$$











Closing remarks

Results achieved:

- Propose a framework for evaluating and studying prospect dependencies, while maintaining statistical computational benefits
- Indicate a guideline for interpreting the results coming from two indices, Vol and AR.

Main bottlenecks:

- 1 The definition of the network and the specification of the parameters
- ② The evaluation criterion to choose: based on different utility functions (higher moments of the distribution).
- Ombinatorial problems: these criteria run very fast, but more complex criteria, that involve dynamic programming, have exponential complexity in the number of segments.

Closing remarks

Current work:

- Understanding and improving in our case the Junction Tree Algorithm, that allows the propagation of the evidence through the network.
- Proposing different criteria and a strategy for sequential planning rather than simultaneous planning [Bickel and Smith, 2006].
- 3 Work under the assumption of imperfect information [Eidsvik et al., 2008]
- 4 Evaluating the sensitivity to the network's structure.
- Overcoming some model limitations (discreteness, elicitation of parameters,...)

Acknowledgements:

- We thank Statoil for providing the expertise and the data necessary to perform this study.
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